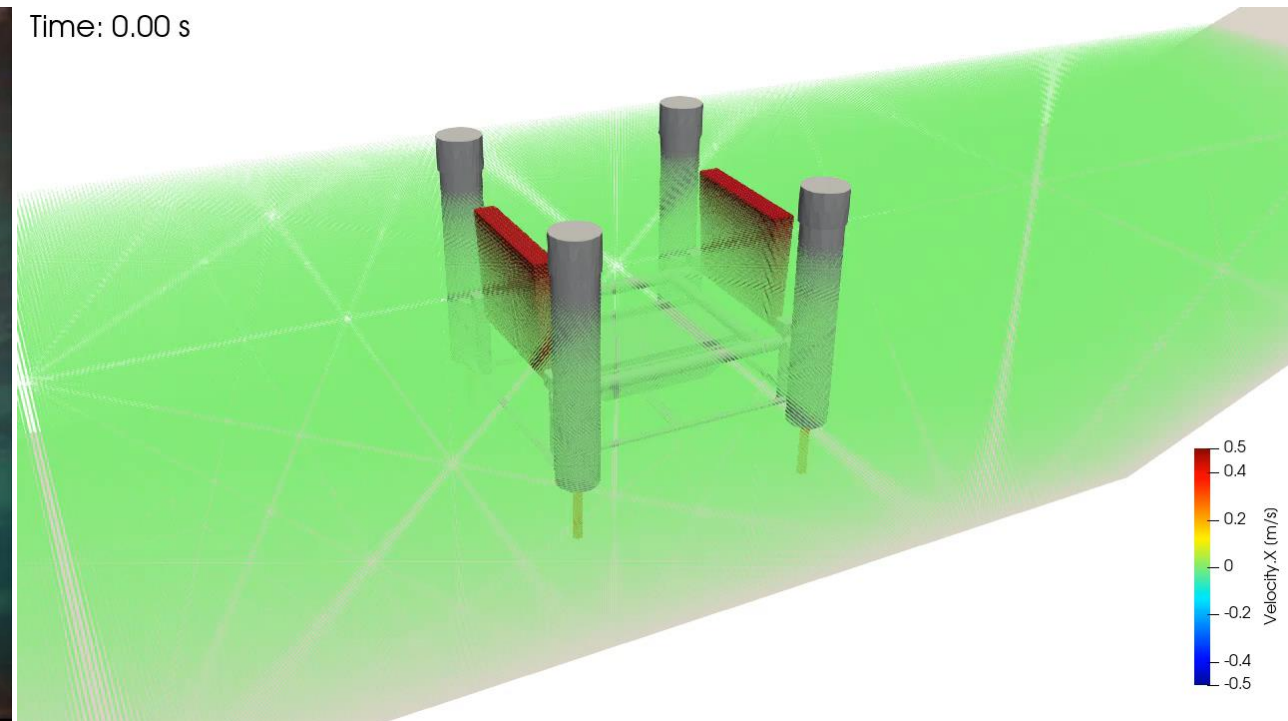
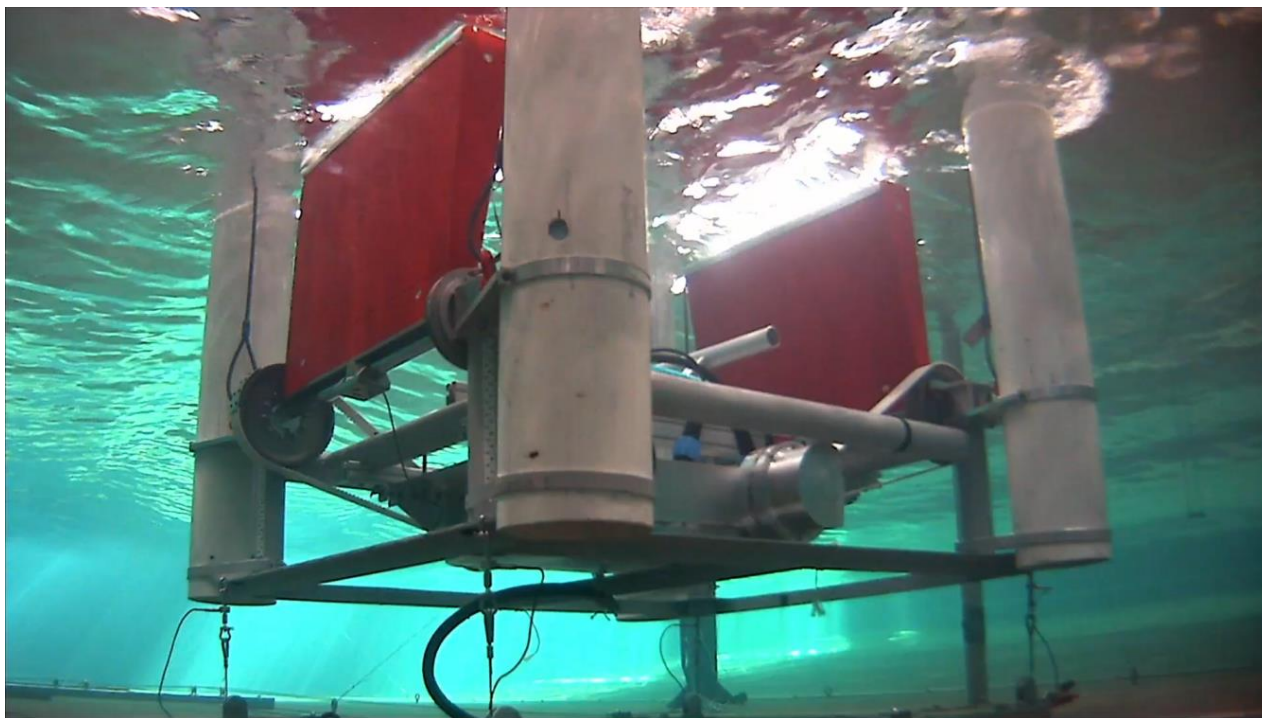
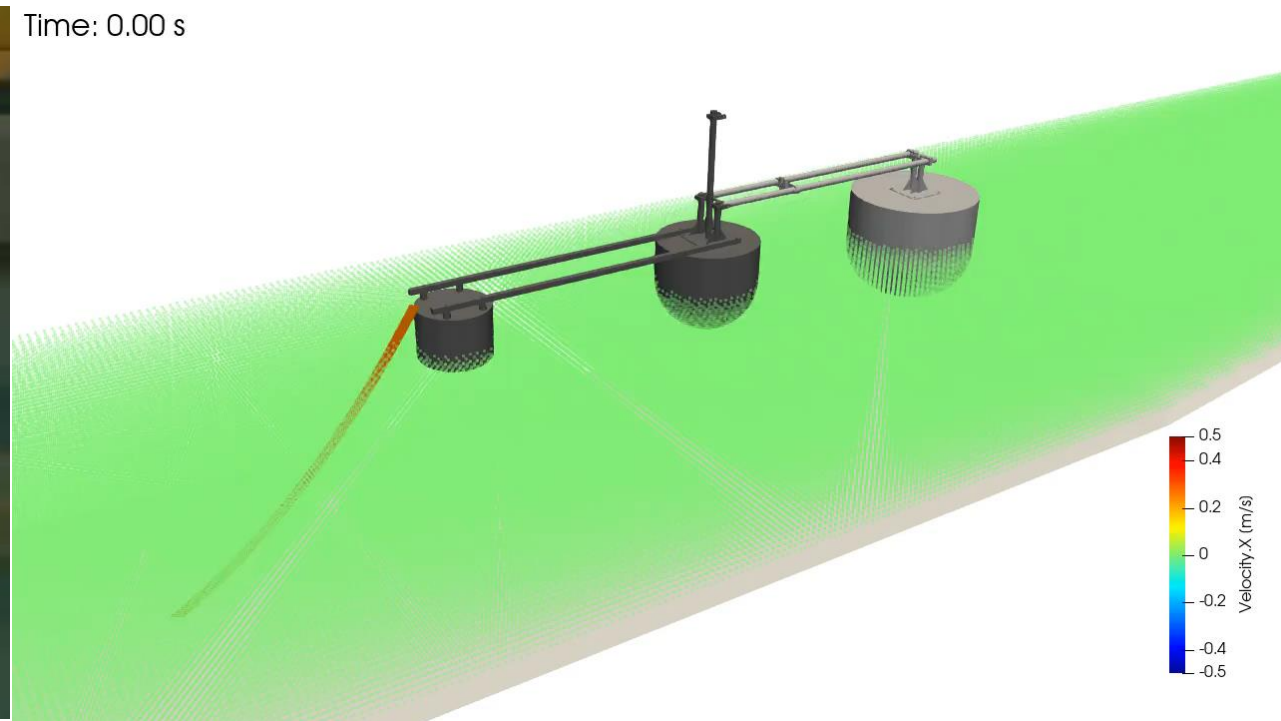


# On the state-of-the-art of CFD simulations for WECs within the open-source numerical framework of DualSPHysics



Alejandro J. Crespo (*CIM-Universidade de Vigo, Spain*)

# On the state-of-the-art of CFD simulations for WECs within the open-source numerical framework of DualSPHysics



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# MOTIVATION

## CHALLENGES OF WAVE ENERGY:

No unanimity on the **WEC technologies** (*Falcão et al., 2010*)

**Optimal PTO** in operating conditions (*Ahamed et al., 2020*)

**Survivability** and maintenance of WECs (*Guo et al., 2021*)

Performance **under extreme wave** loadings (*Guo et al., 2021*)

**High upfront costs** of wave energy (*Guo et al., 2023*)

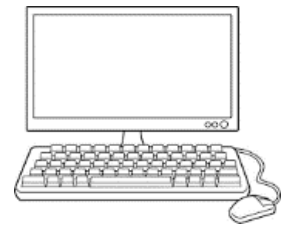


*FMARMOK-A-5 device,  
developed by **Oceantec**,  
during its installation at BiMEP*

## NUMERICAL MODELLING IS A KEY TO ADDRESSING THESE CHALLENGES

Data provides **valuable insights** and pushes forward the development of WEC designs

WEC problems are **highly complex and non-linear**, in particular for **survivability** studies



## OUR APPROACH

Meshless **SPH** method for **violent flows** with rapidly moving or **fluid-driven devices**

**DualSPHysics v5.2** is applied to **four well-established WEC concepts**

Study of not only the **efficiency** but also the **survivability** of WECs.

We provide a **free numerical tool** into simulating **other novel WEC devices**

# OUTLINE

## **1. Numerical modelling of WECs**

### **1.1 Meshless CFD and SPH**

### **1.2 DualSPHysics open-source code**

### **1.3 Coupling with other solvers**

## **2. Simulation of different WEC technologies**

### **2.1 Uppsala Point Absorber**

### **2.2 Oscillating Wave Surge Converter**

### **2.3 Floating Oscillating Surge Wave Energy Converter**

### **2.4 Multi-float M4**

## **3. Work undergoing**

### **3.1 More WEC technologies**

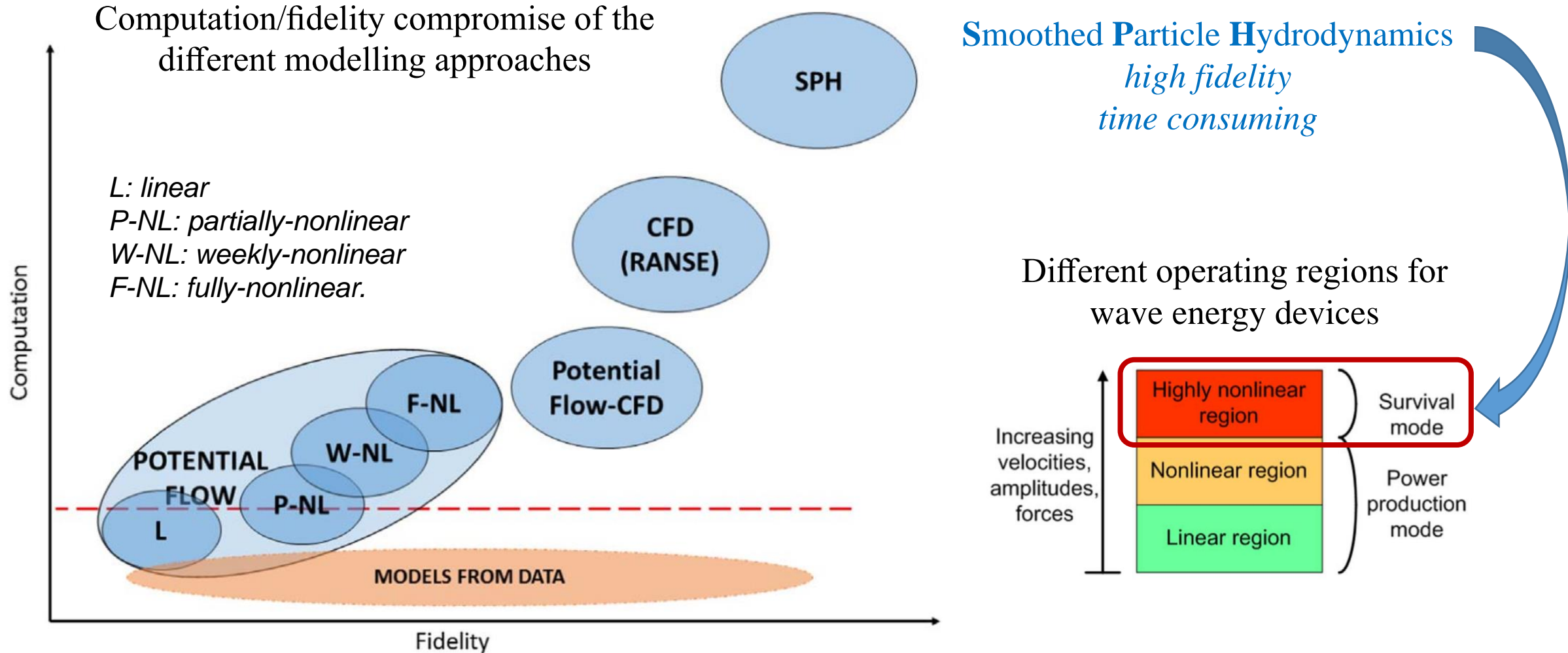
### **3.2 Active control systems**

### **3.3 Flexible WECs**

## **4. Conclusions**

# 1.1 Meshless CFD and SPH

## Numerical modelling of the hydrodynamic interaction wave-WECs

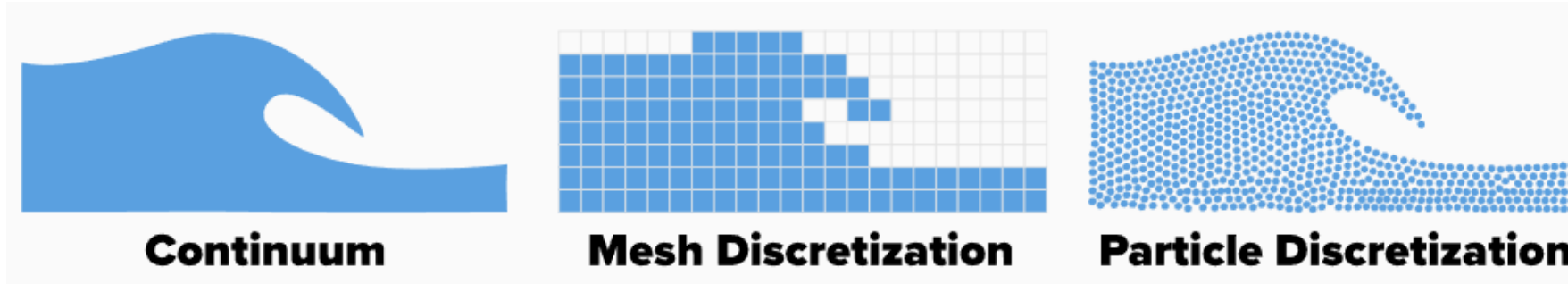


Source: *Penalba et al., 2017*

# 1.1 Meshless CFD and SPH

## Smoothed Particle Hydrodynamics

**Meshless** Our computation points are **particles** that now **move** according to governing dynamics



Source: <https://www.dive-solutions.de/blog/sph-basics>

**Particles** possess **fluid properties** that travel with them, e.g., density, pressure; these can change with time

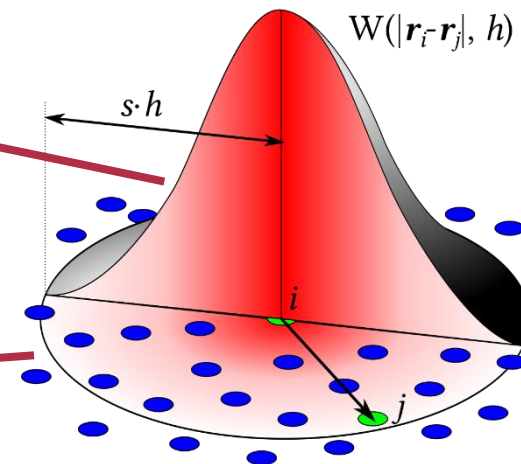
**Local Interpolation** (summation) with a **weighting function (Kernel)** around each particle to obtain fluid properties

$$A_i = \sum_{j=1}^N A_j W(|r_i - r_j|, h) \frac{m_j}{\rho_j}$$

**KERNEL  
FUNCTION**

**KERNEL  
FUNCTION**

**COMPACT  
SUPPORT**



Source: [Wikipedia \(CC BY-SA 4.0\)](#)

# 1.1 Meshless CFD and SPH

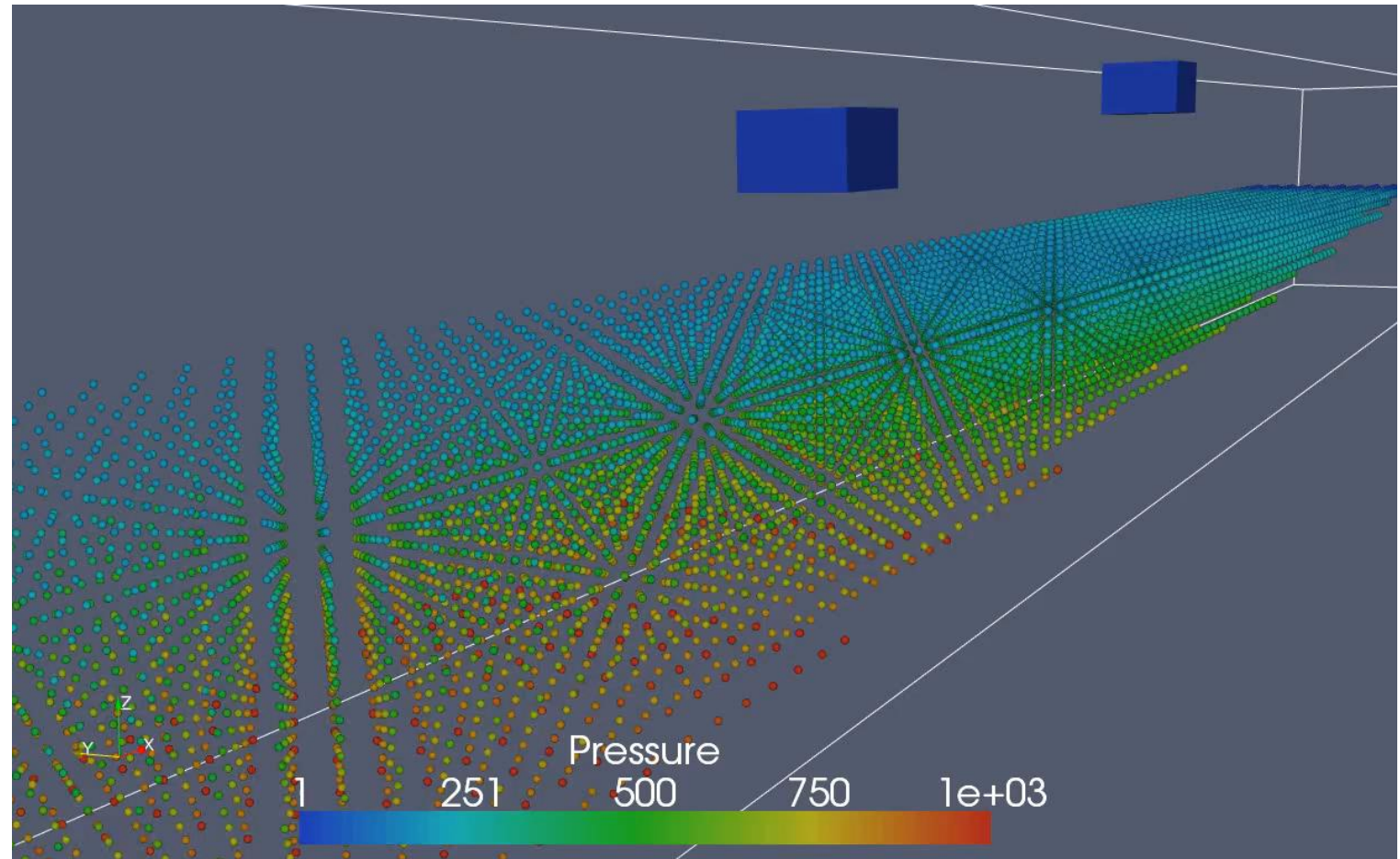
## Smoothed Particle Hydrodynamics

Navier-Stokes momentum equation

Continuity equation + density diffusion terms

WCSPH: equation of state

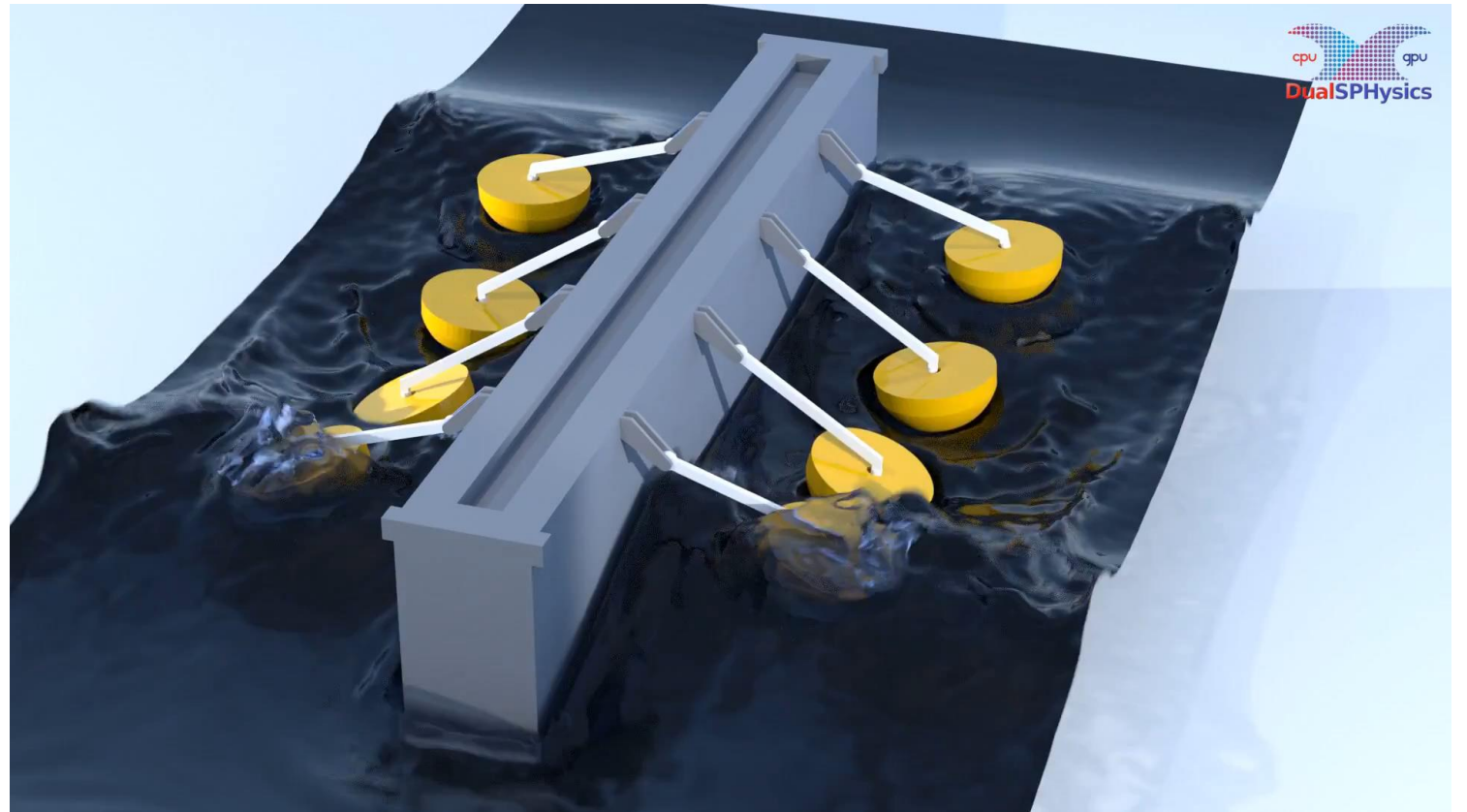
particles = moving computational nodes



# 1.1 Meshless CFD and SPH

## Smoothed Particle Hydrodynamics

- **Easy to set up**, no mesh, particles conform to body in still water automatically
- Efficient treatment of the **large deformation of free surfaces** (no mesh distortion)
- **Avoids** computation of the **nonlinear advection terms** thanks to its Lagrangian formulation
- **Waves and currents easy to input**, as mesh methods
- Method inherently **stable and robust**





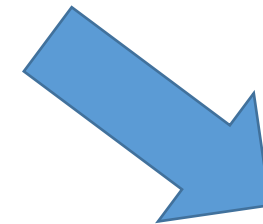
# 1.1 Meshless CFD and SPH

## Smoothed Particle Hydrodynamics

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### **DISADVANTAGES comparing with mesh-based CFD codes:**

- There is still **no unanimity** to choose the best **solid boundary** conditions
- **Turbulence** treatment is still an **open field** and more research is needed
- Time **computation is expensive** comparing with other methods



## 1.2 DualSPHysics open-source code



OPEN-SOURCE CODE

COLLABORATIVE PROJECT

LGPL LICENSE

RIGOROUSLY VALIDATED

HIGHLY PARALLELISED

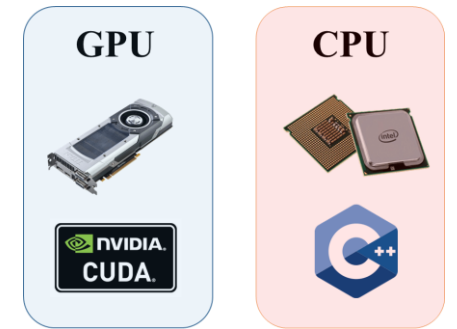
PRE- & POST-PROCESSING

APPLIED TO REAL PROBLEMS

DualSPHysics Code on GitHub  
<https://github.com/DualSPHysics/DualSPHysics>

+120.000 downloads

*Universidade de Vigo, Spain*  
*The University of Manchester, UK*  
*Università degli studi di Parma, Italy*  
*Universitat Politècnica de Catalunya*  
*New Jersey Institute of Technology, USA*



GPU  CPU  
x100

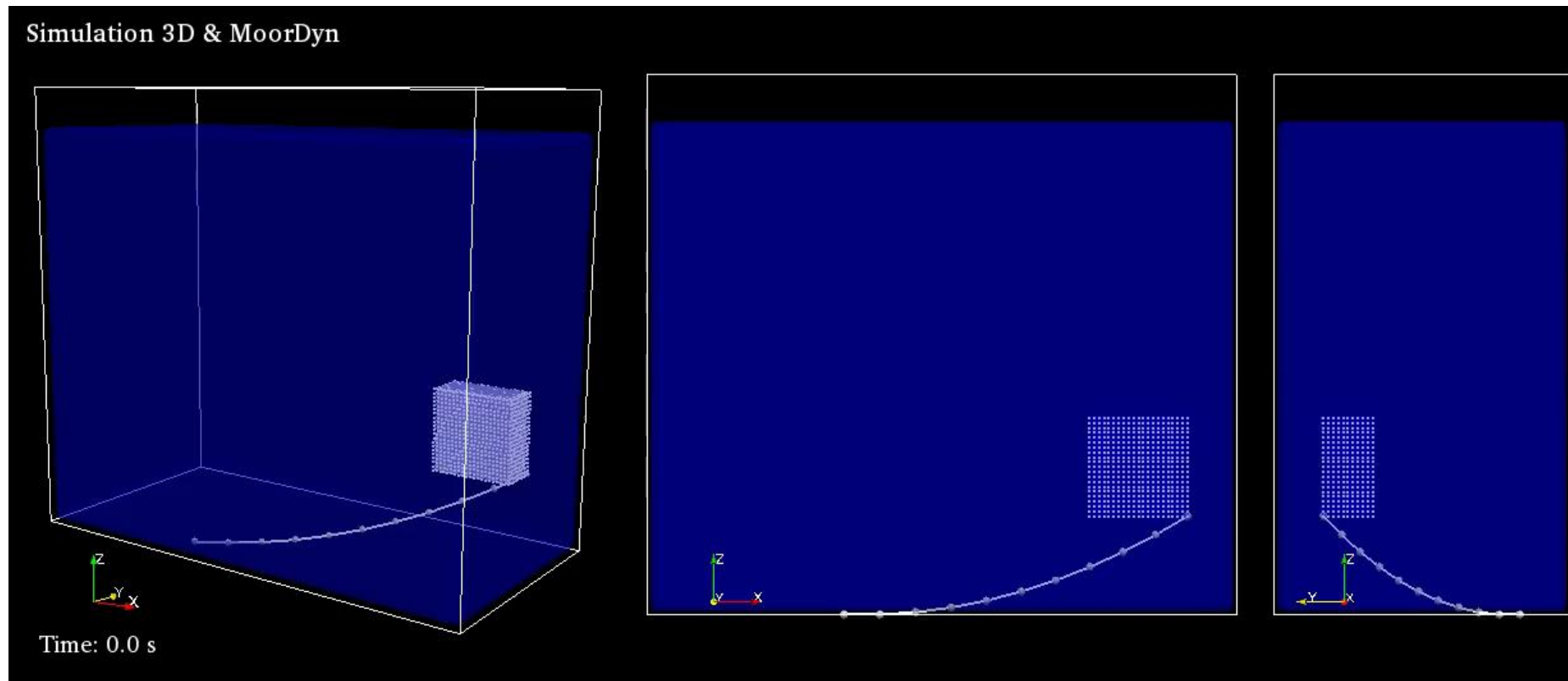


## 1.3 Coupling with other solvers

### Coupling with MoorDyn+ solver

**MoorDyn+** (based on **MoorDyn**) is a dynamic **mooring** line model that uses a lumped-mass formulation:

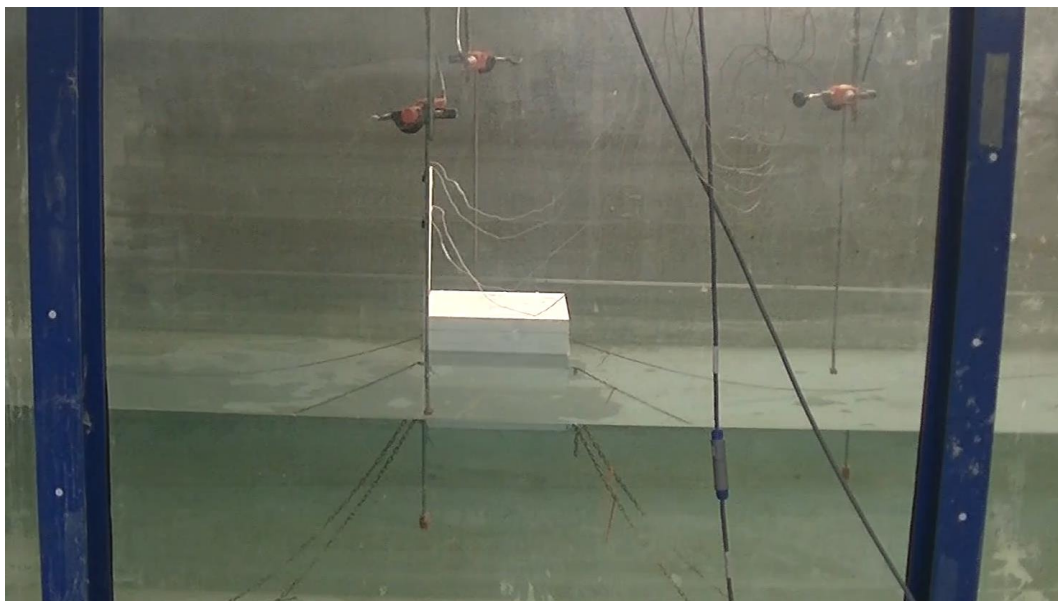
- *Solves catenary equation*
- *Considers axial stiffness and friction with the bottom*
- *Use of different water depths in the same simulation*
- *Mooring connected to more than one floating object*



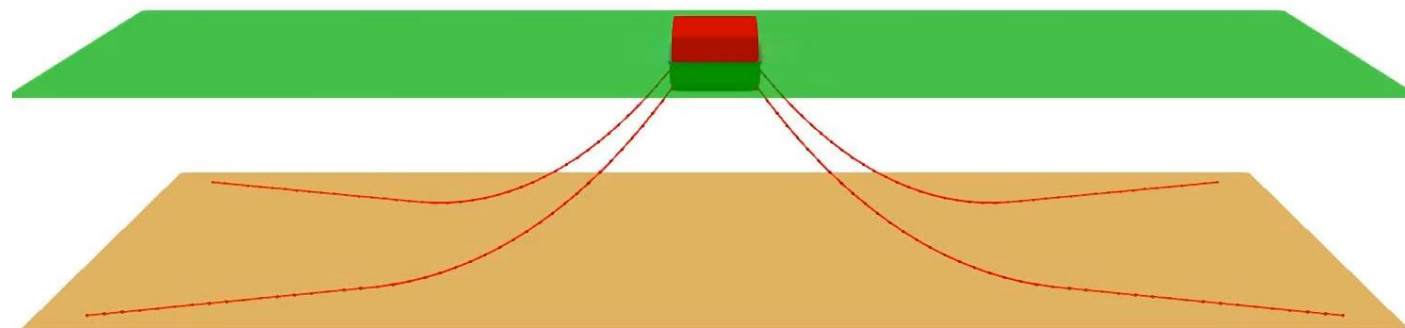
# 1.3 Coupling with other solvers

## Coupling with MoorDyn+ solver

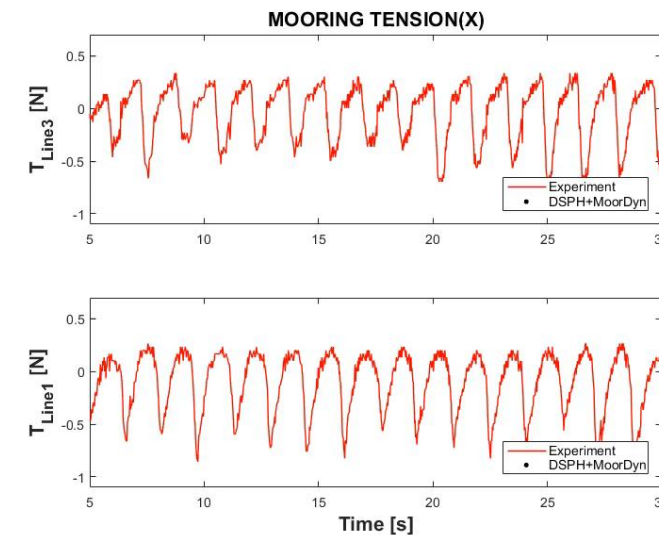
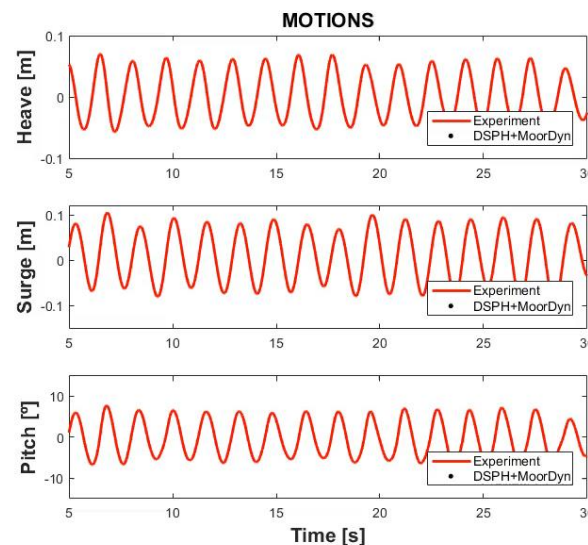
Floating moored BOX  
Regular waves; H=0.12 m, T=1.6s, d=0.5m



Time: 0.02 s



Parameter	Value
box length	20 cm
box width	20 cm
box height	13.2 cm
box weight (+ connections)	3.6 kg
centre of gravity of the box (X,Y,Z)	(0, 0, -1.26) cm
box lip draught	7.86 cm
mooring diameter	3.656 mm
mooring weight (per length)	0.607 g/cm
mooring length	145.5 cm



## 1.3 Coupling with other solvers

### Coupling with Project Chrono library

#### **MULTIBODY DYNAMICS**

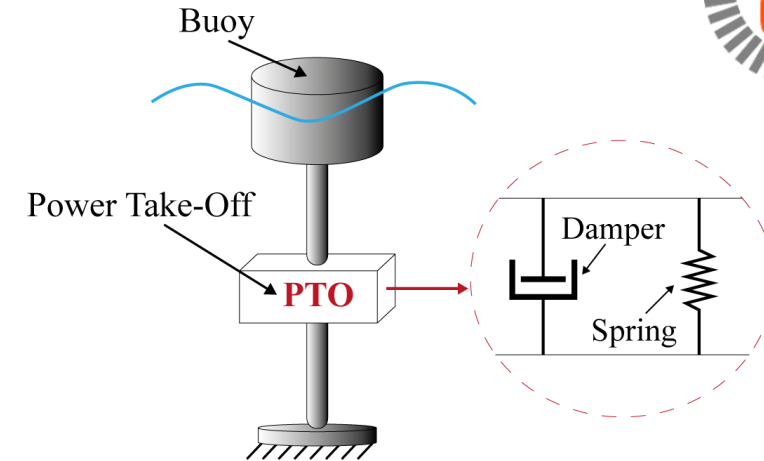
Mechanical constraints between rigid and flexible objects  
Add motors, linear actuators, springs and dampers.  
Apply forces and torques.

#### **COLLISION DETECTION**

Define collision shapes using meshes or primitives.  
Compute frictional contact forces using state-of-the-art collision detection algorithms.  
Define surface/material properties.

#### **FINITE ELEMENTS**

Use the FEA module to create finite elements and model flexible parts.  
Beams, cables, shells, solid tetrahedrons and hexahedrons.



## 1.3 Coupling with other solvers

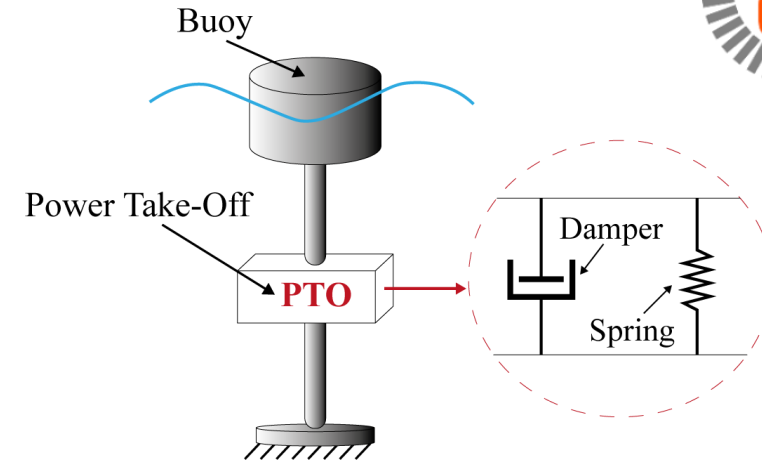
<http://projectchrono.org>



### Coupling with Project Chrono library

#### MULTIBODY DYNAMICS

Mechanical constraints between rigid and flexible objects  
Add motors, linear actuators, springs and dampers.  
Apply forces and torques.



#### Translational Spring-Damper-Actuator (TSDA)

Spring with stiffness and damping in CHRONO:

$$F_{PTO} = k(d - l) + c \cdot v$$

$d$ : distance between the two origins

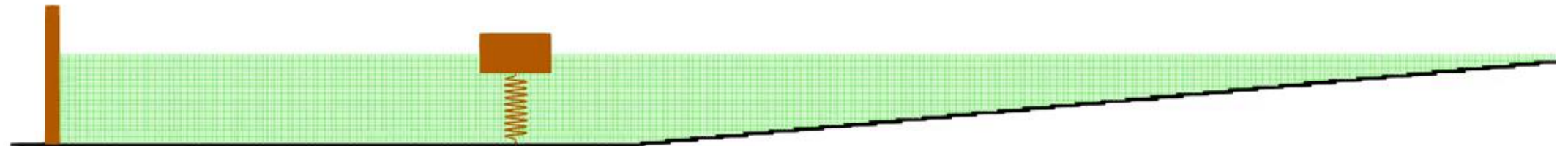
$l$ : equilibrium length

$v$ : velocity experienced by spring

$k$ : stiffness coefficient

$c$ : damping coefficient

#### CasePointAbsorberSpring



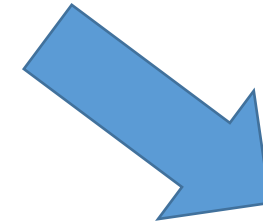
# 1.1 Meshless CFD and SPH

## Smoothed Particle Hydrodynamics

- **Easy to set up**, no mesh, particles conform to body in still water automatically
- Efficient treatment of the **large deformation of free surfaces** (no mesh distortion)
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- **Waves and currents easy to input**, as mesh methods
- Method inherently **stable and robust**

### **DISADVANTAGES comparing with mesh-based CFD codes:**

- There is still **no unanimity** to choose the best **solid boundary** conditions
- **Turbulence** treatment is still an **open field** and more research is needed
- Time **computation is expensive** comparing with other methods



### **USING the open-source DualSPHysics package:**

- Coupling with Chrono for structural constraints and MoorDyn available, so flexible
- Speeds on GPU similar to mesh methods



# OUTLINE

## **1. Numerical modelling of WECs**

### **1.1 Meshless CFD and SPH**

### **1.2 DualSPHysics open-source code**

### **1.3 Coupling with other solvers**

## **2. Simulation of different WEC technologies**

### **2.1 Uppsala Point Absorber**

### **2.2 Oscillating Wave Surge Converter**

### **2.3 Floating Oscillating Surge Wave Energy Converter**

### **2.4 Multi-float M4**

## **3. Work undergoing**

### **3.1 More WEC technologies**

### **3.2 Active control systems**

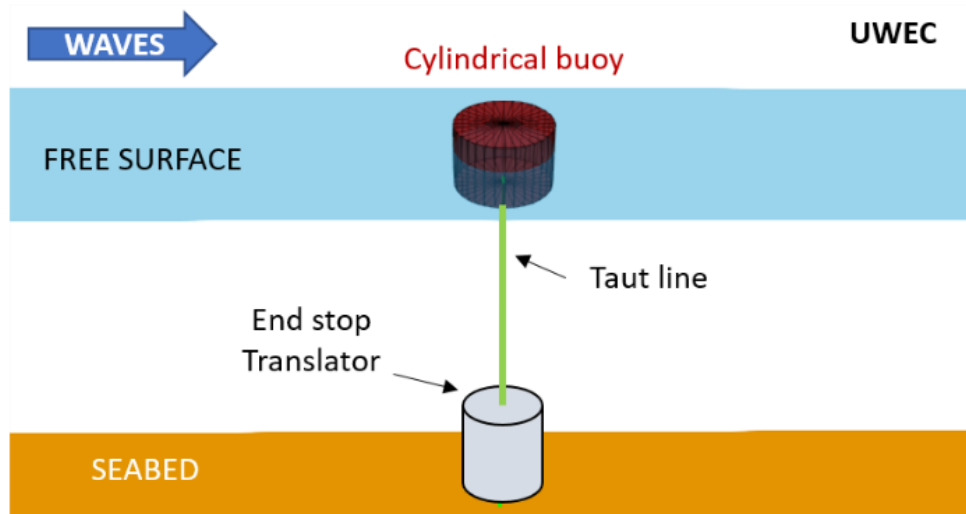
### **3.3 Flexible WECs**

## **4. Conclusions**

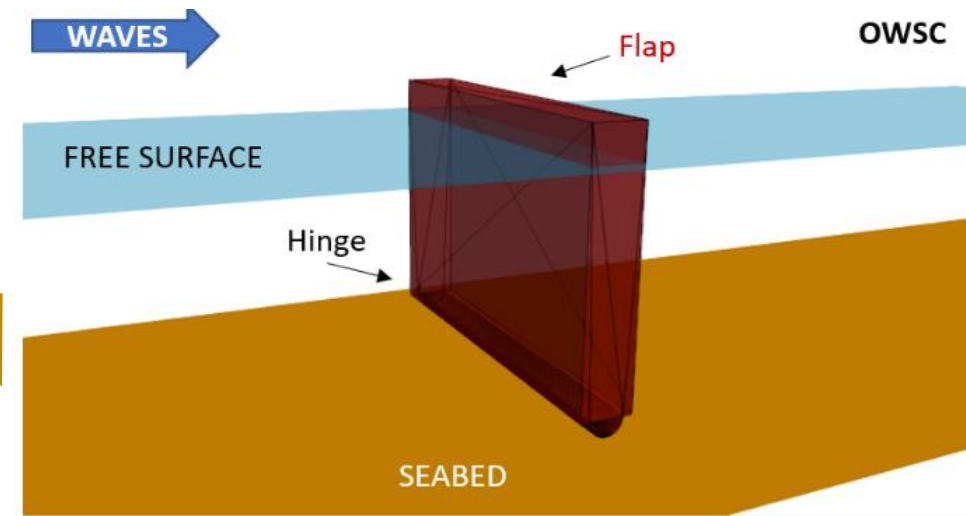


## 2. Simulation of different WEC technologies

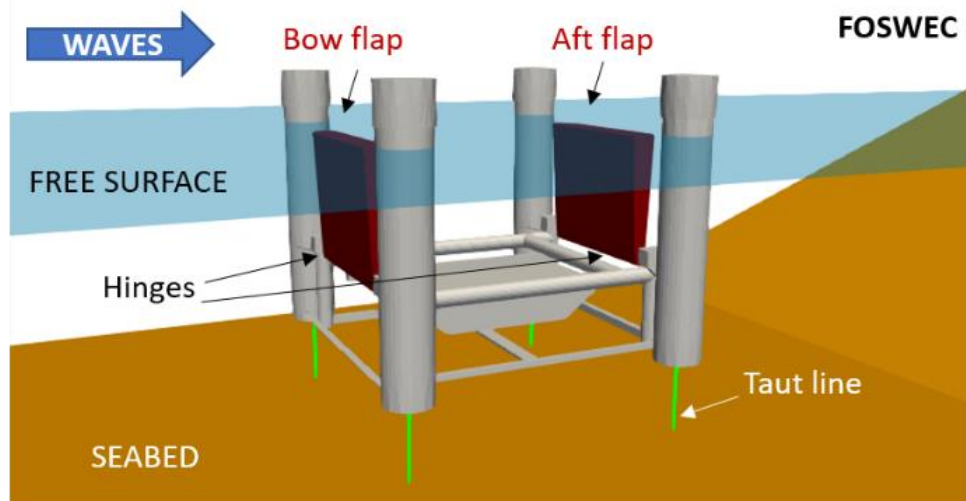
### Uppsala Point Absorber



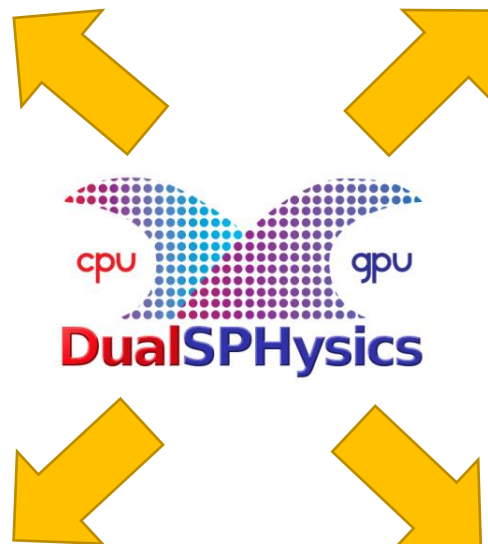
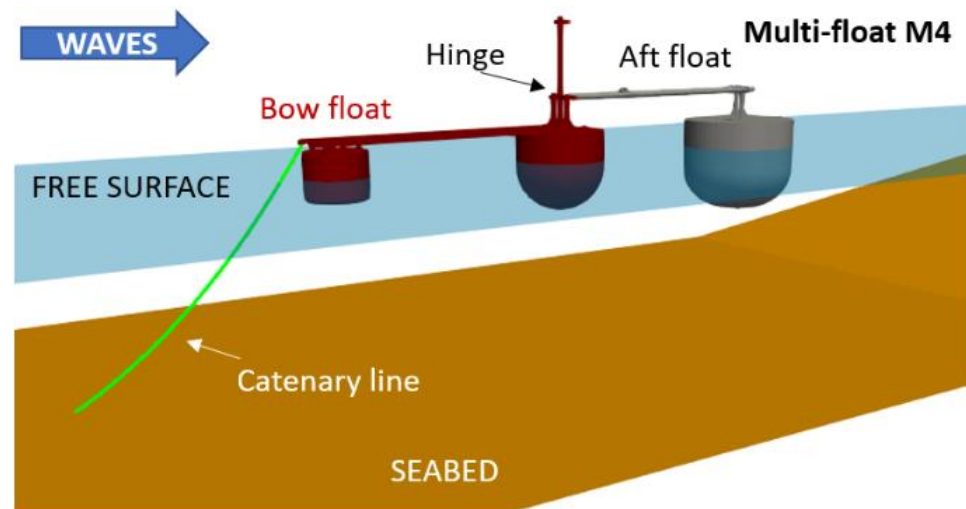
### Oscillating Wave Surge Converter



### Floating Oscillating Surge WEC



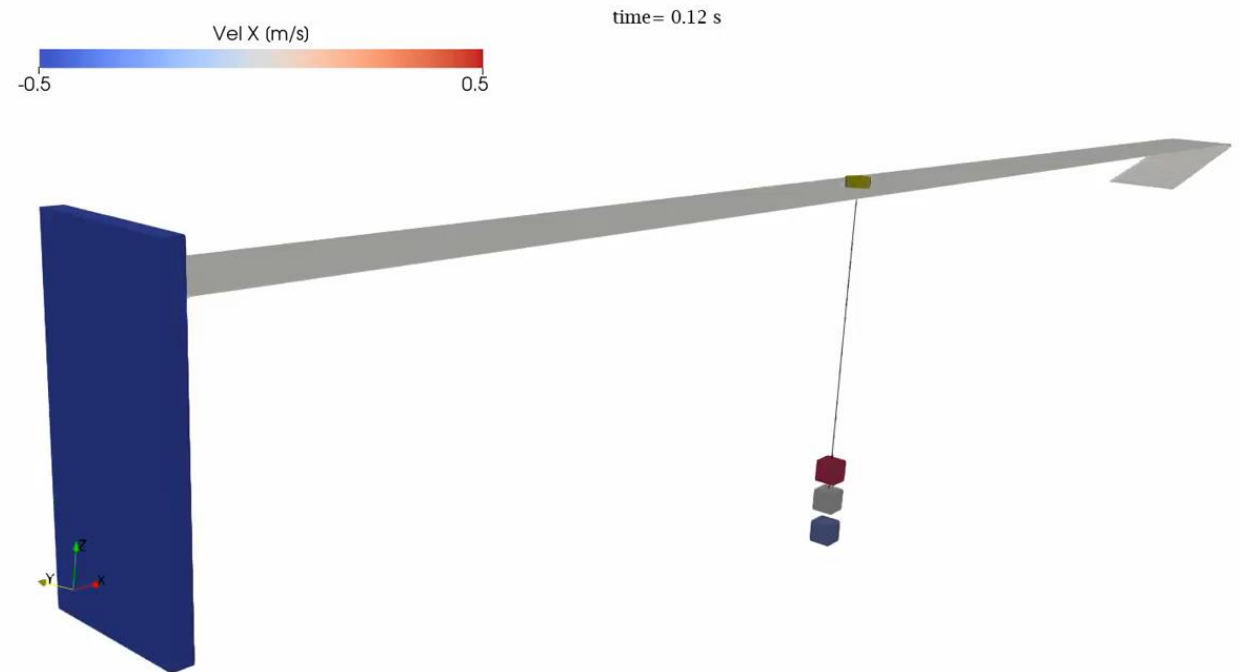
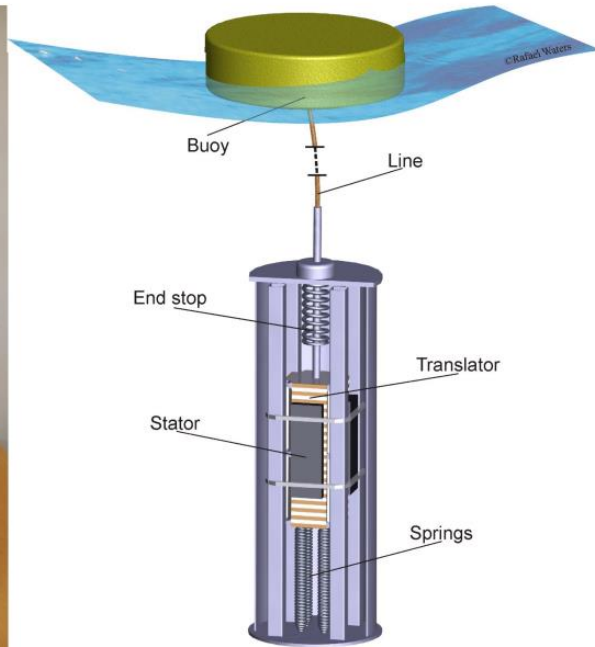
### Multi-float M4



## 2.1 Uppsala Point Absorber

### WEC concept and experiments

- **Floating buoy** and a linear magnet generator (PTO) **connected via a line**.
- The generator is attached on a **ballasted platform** fixed at the seabed.



Source: *Göteman et al., 2015*

*The model is asserted by friction brakes acting on the translator*



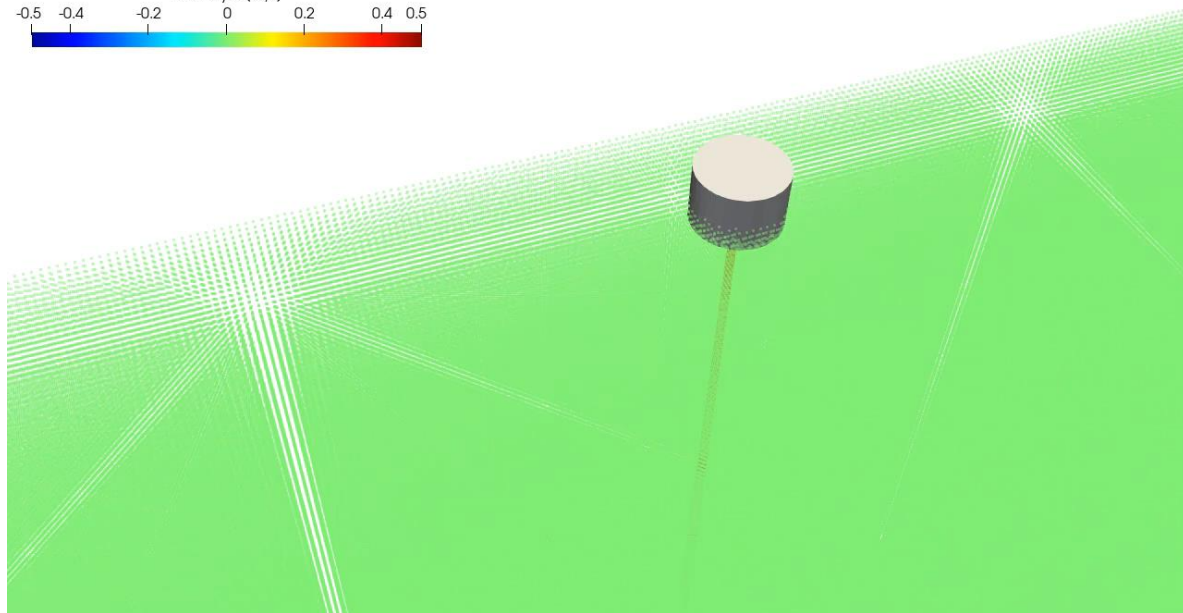
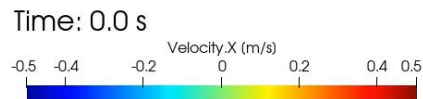
*A taut mooring line transmits the rectified motion of the buoy to the translator*



**MoorDyn+**

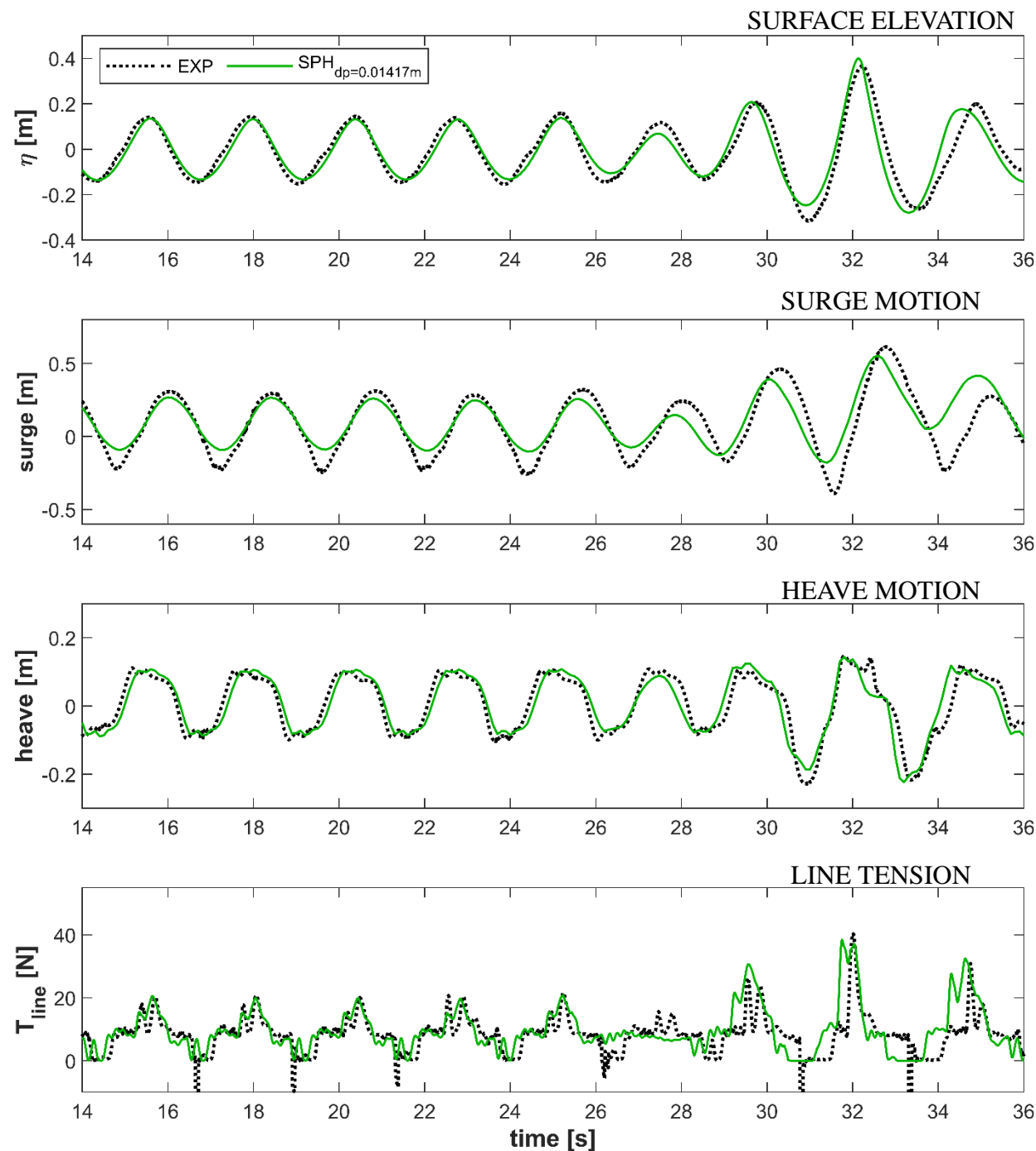
# 2.1 Uppsala Point Absorber

## Validation using DualSPHysics v5.2



Focused wave train ( $H_{focus}=0.38$  m,  $T_{focus}=2.604$  s)  
 embedded into regular wave background ( $H=0.27$  m,  $T=2.4$  s)  
 PTO configuration with only internal **damping** (2.79 Ns/m)

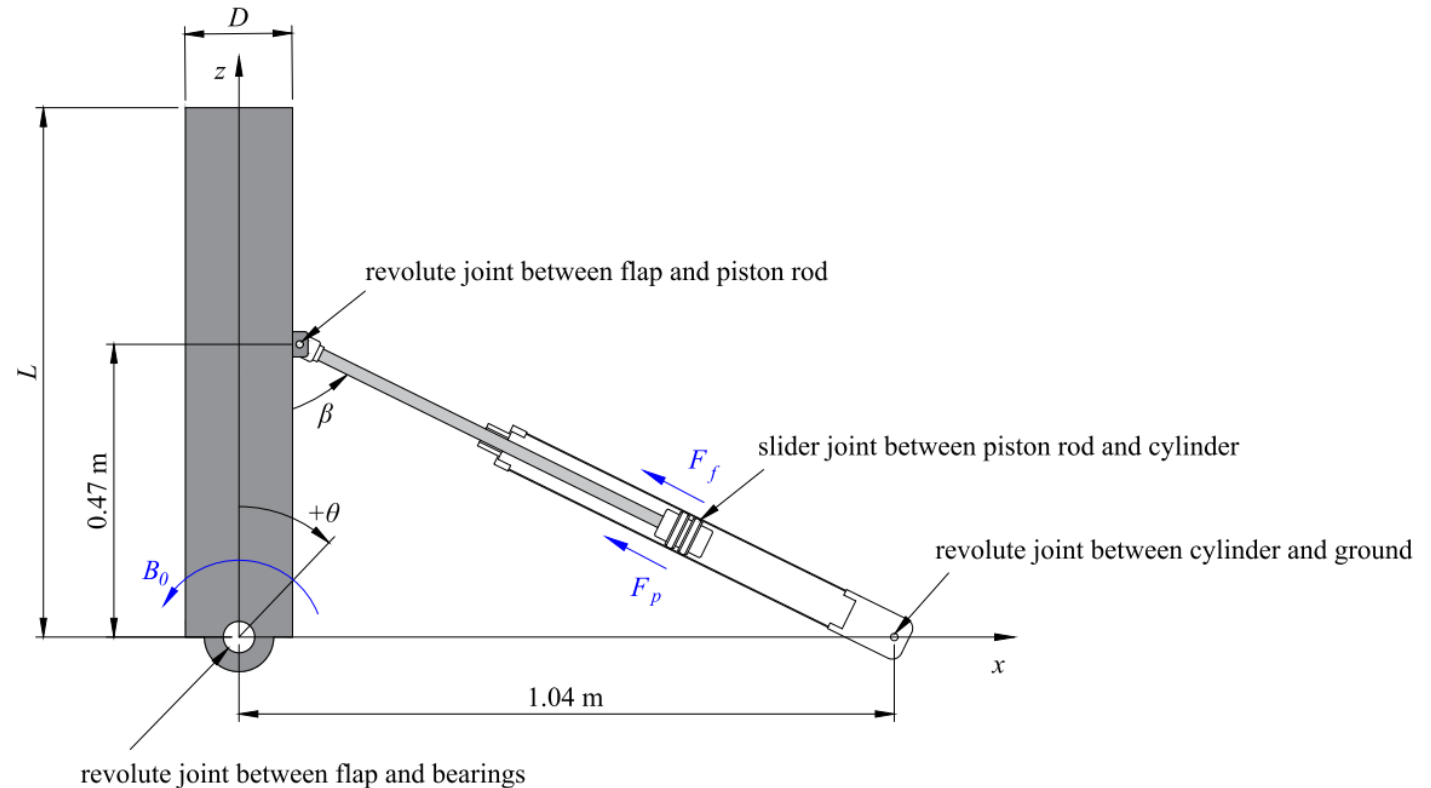
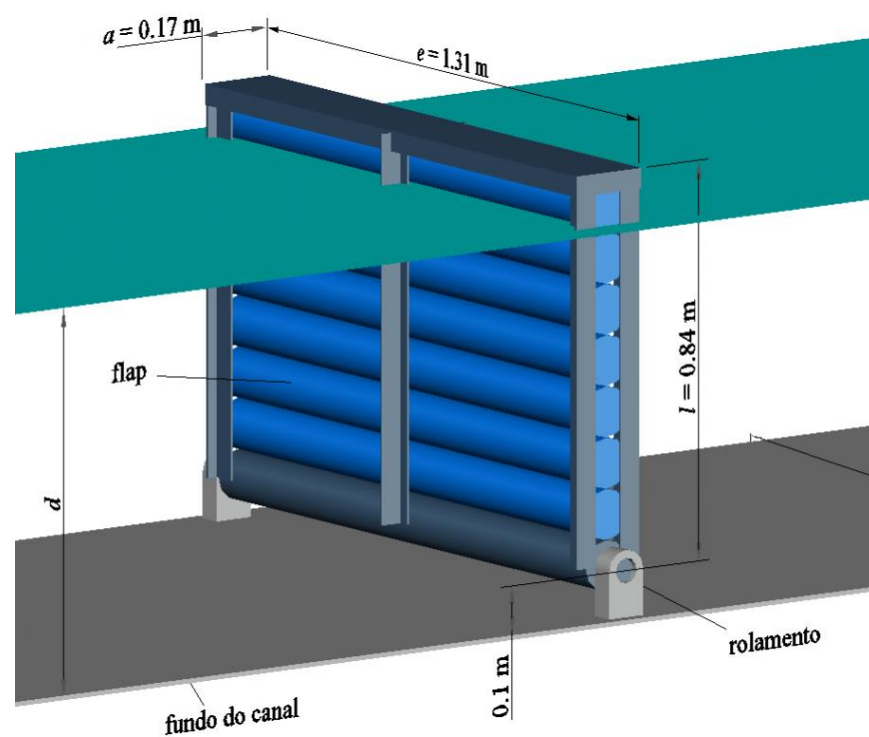
$dp$ [m]	0.0425	0.02125	0.01417
$H/dp$	8.47	16.94	25.41
particles	$2.03 \cdot 10^5$	$1.89 \cdot 10^6$	$6.43 \cdot 10^6$
runtime	1.0 h	10.6 h	48.3 h
runtime/second	1.5 min	16.8 min	1.3 h



## 2.2 Oscillating Wave Surge Converter

### WEC concept and experiments

- OWSCs are designed to **harness wave energy** nearshore through the **oscillatory pitch motion of a flap**.
- The **flap** consists of PVC tubes joined by a stainless steel frame, and a bearing, and it is **hinged width-wise above the bed**.



Source: *Brito et al., 2017*

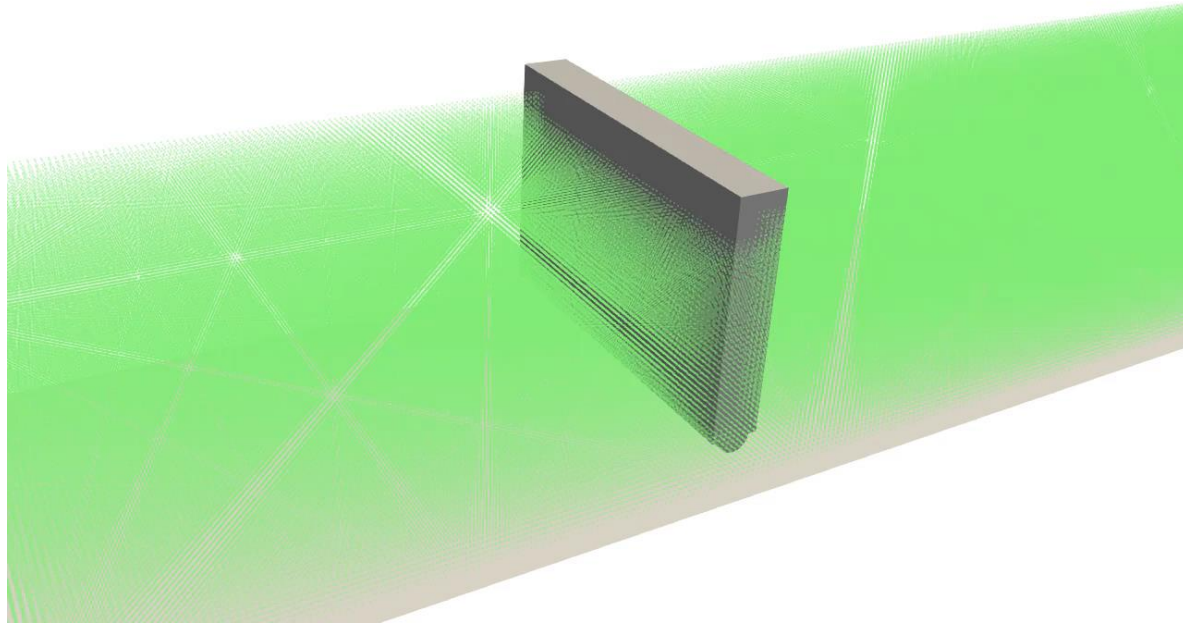
*The PTO system: equivalent torque (to the one on the revolute joint) generated by a linear force following a Coulomb damping behaviour*



# 2.2 Oscillating Wave Surge Converter

## Validation using DualSPHysics v5.2

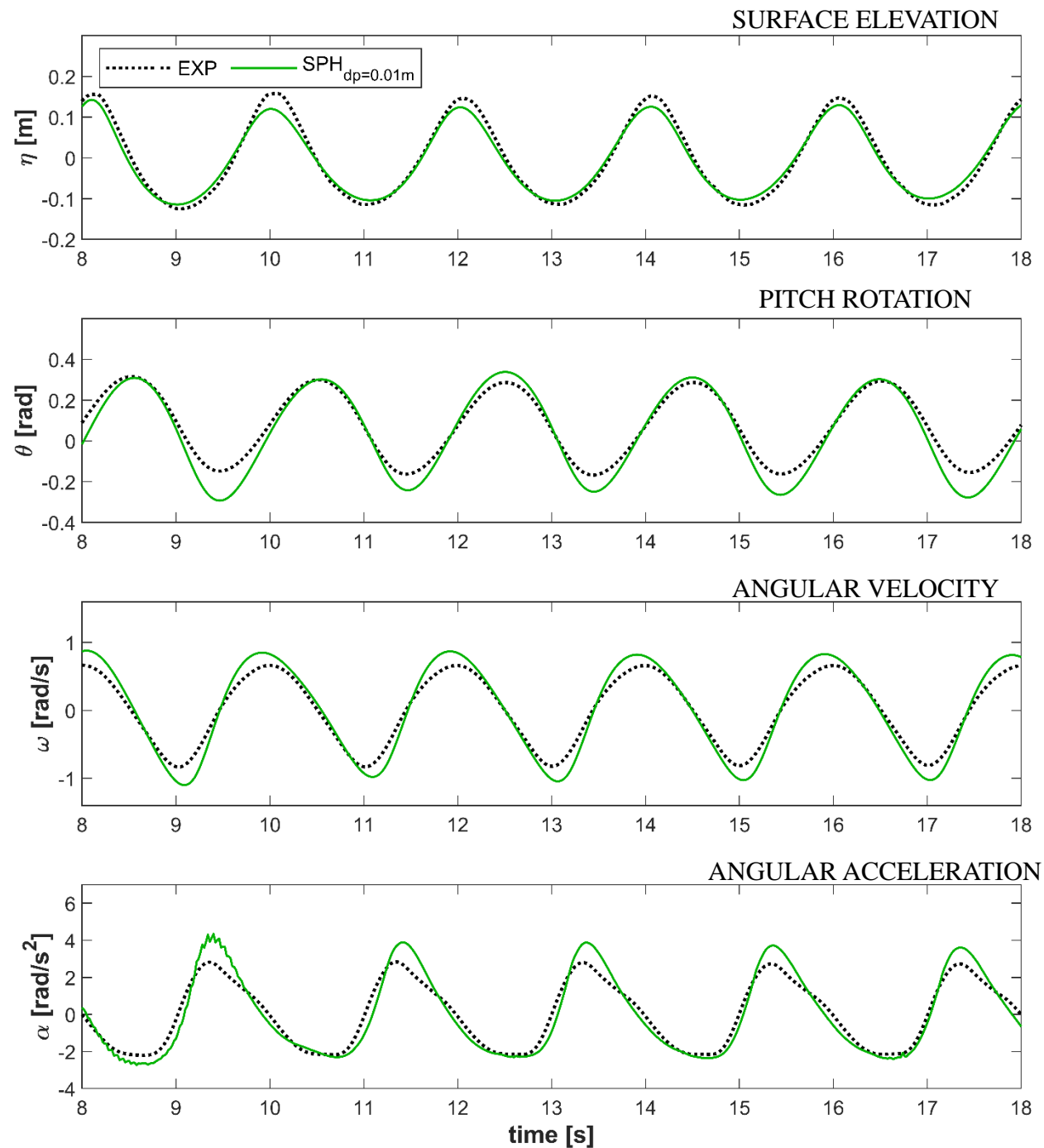
Time: 0.00 s



Regular wave ( $H=0.25$  m,  $T=2$  s, depth= $0.825$  m)



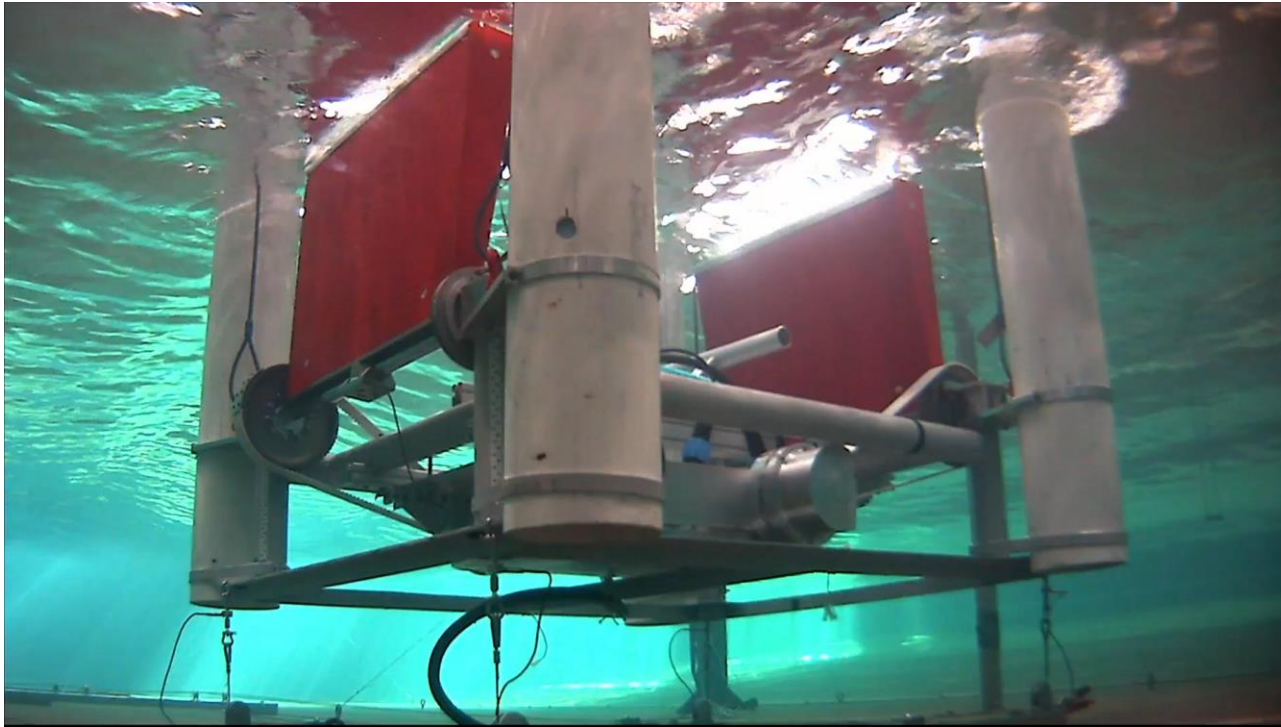
$dp$ [m]	0.03	0.02	0.01
$H/dp$	8.33	12.50	25.00
particles	$1.20 \cdot 10^6$	$3.87 \cdot 10^6$	$2.92 \cdot 10^7$
runtime [h]	1.4 h	6.4 h	91.2 h
runtime/second	4.2 min	16.9 min	4.6 h



## 2.3 Floating Oscillating Surge Wave Energy Converter

### WEC concept and experiments

- FOSWEC is a **dualflap** device with a submerged central platform serving as the host for the two flaps.
- The flaps are hinged to **pivot around shafts** mounted to the hull and are controlled by independent motors (PTO).



<https://youtu.be/OUxbaEC2K6Y>

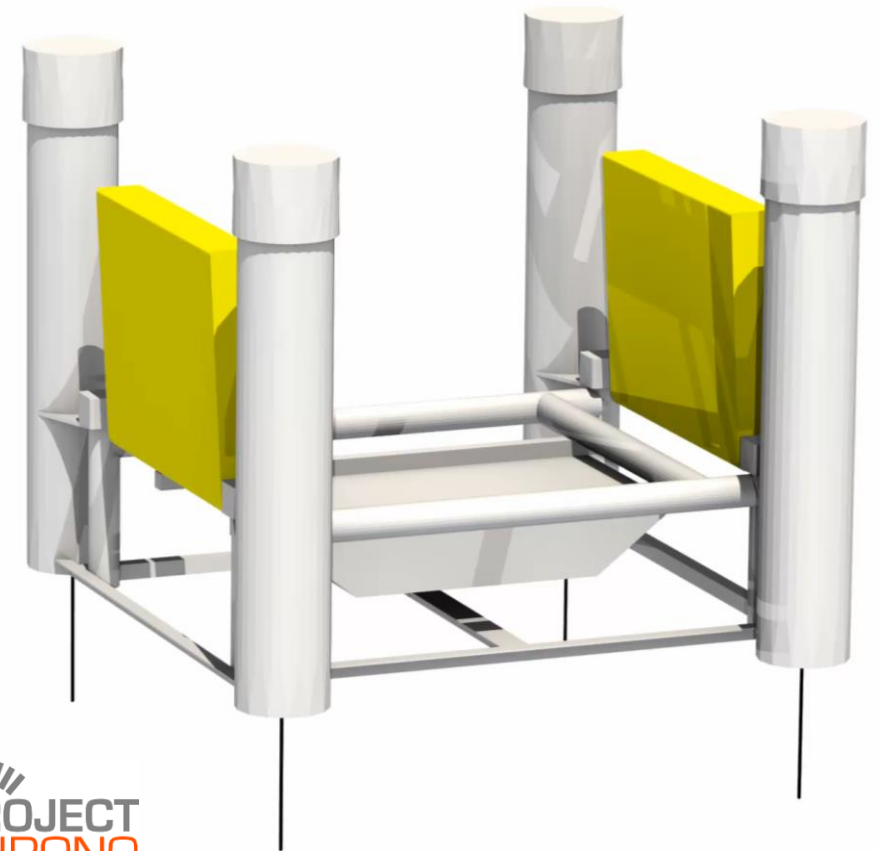
*Stiffness and damping coefficients of the PTO system*



*The hull is anchored by 4 mooring taut vertical lines*



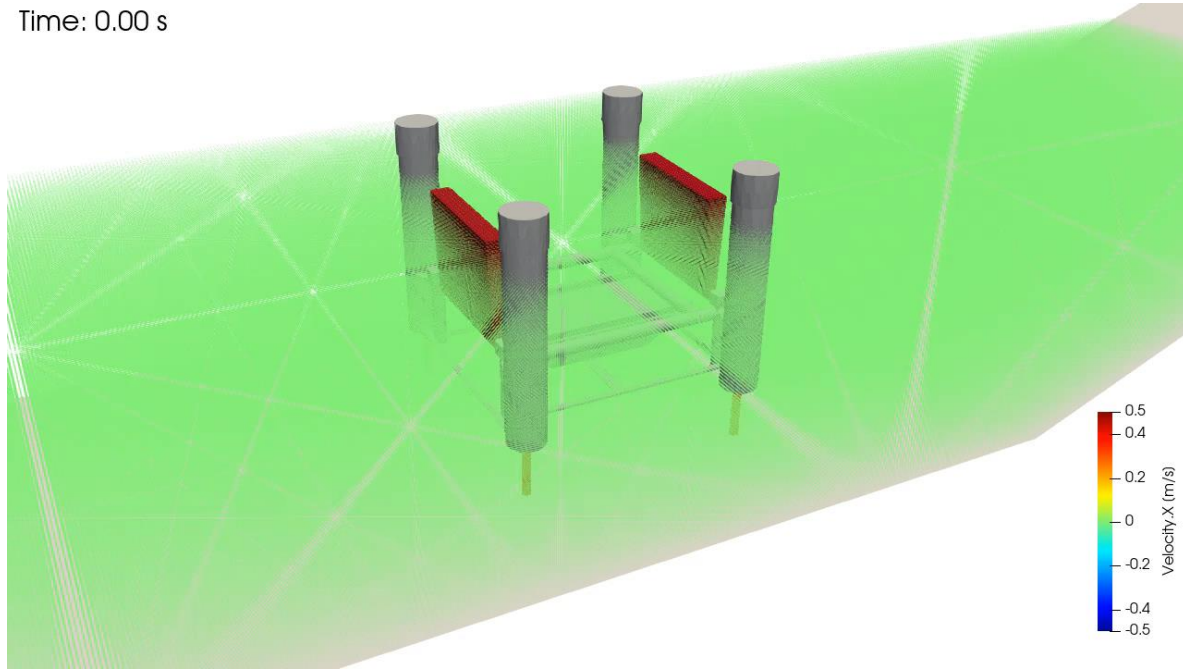
**MoorDyn+**



# 2.3 Floating Oscillating Surge Wave Energy

## Validation using DualSPHysics v5.2

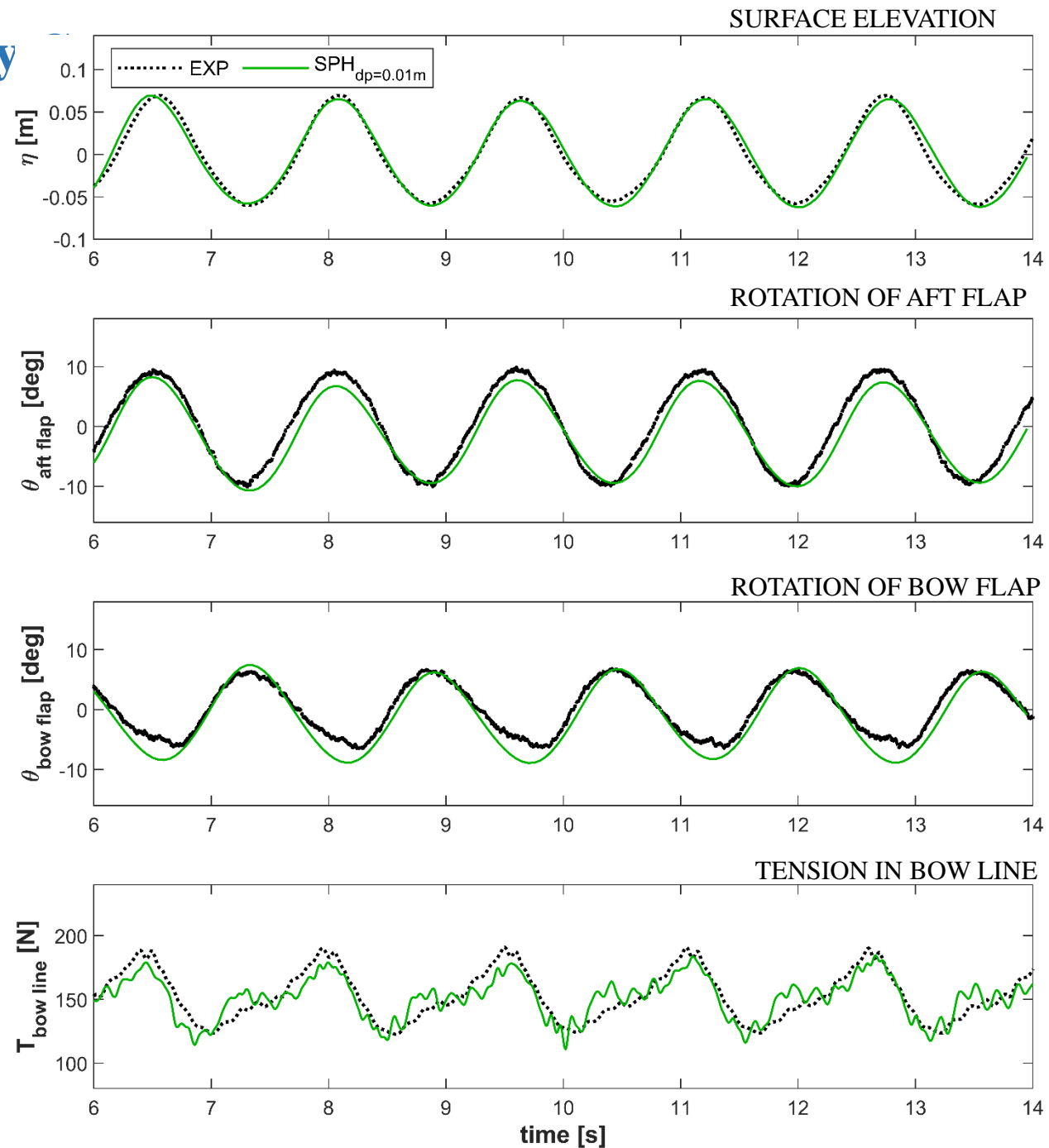
Time: 0.00 s



Regular wave ( $H=0.136$  m,  $T=1.5625$  s, depth=1.36 m)



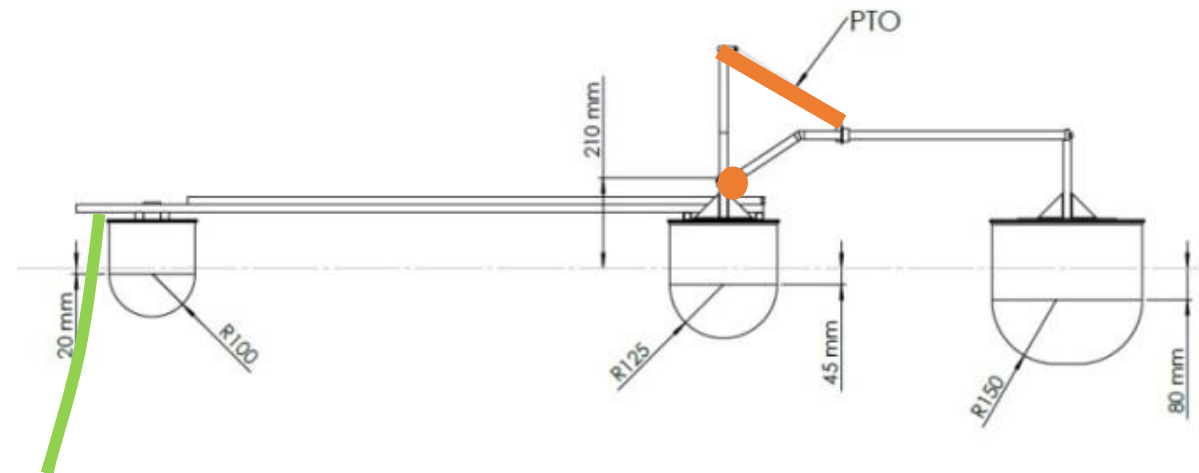
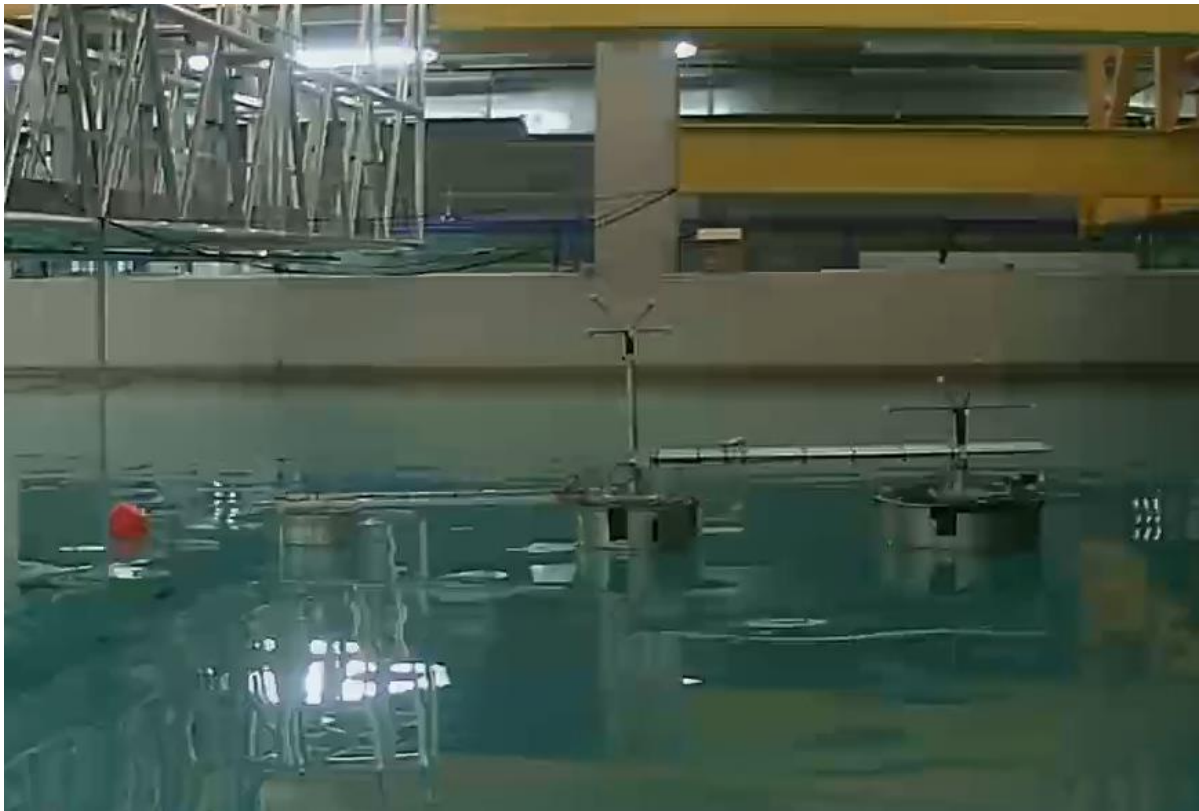
$dp$ [m]	<b>0.03</b>	<b>0.02</b>	<b>0.01</b>
$H/dp$	<b>4.53</b>	<b>6.80</b>	<b>13.60</b>
<i>particles</i>	<b><math>1.45 \cdot 10^5</math></b>	<b><math>4.78 \cdot 10^6</math></b>	<b><math>3.68 \cdot 10^7</math></b>
<i>runtime</i>	<b>1.4 h</b>	<b>6.5 h</b>	<b>100.9 h</b>
<i>runtime/second</i>	<b>6.1 min</b>	<b>28.0 min</b>	<b>7.2 h</b>



## 2.4 Multi-float M4

### WEC concept and experiments

- The multi-float M4 comprises several floats with **multi-mode forcing**.
- The cylindrical floats have **different diameters and drafts** with hemispherical bases.
- The diameters of the floats and their drafts **increase from bow to aft** to facilitate the **alignment** with the wave direction.



Interaction wave-WEC

Mooring line

Mechanical constraint “hinge”

Pneumatic actuator or damper

SPH

MoorDyn+



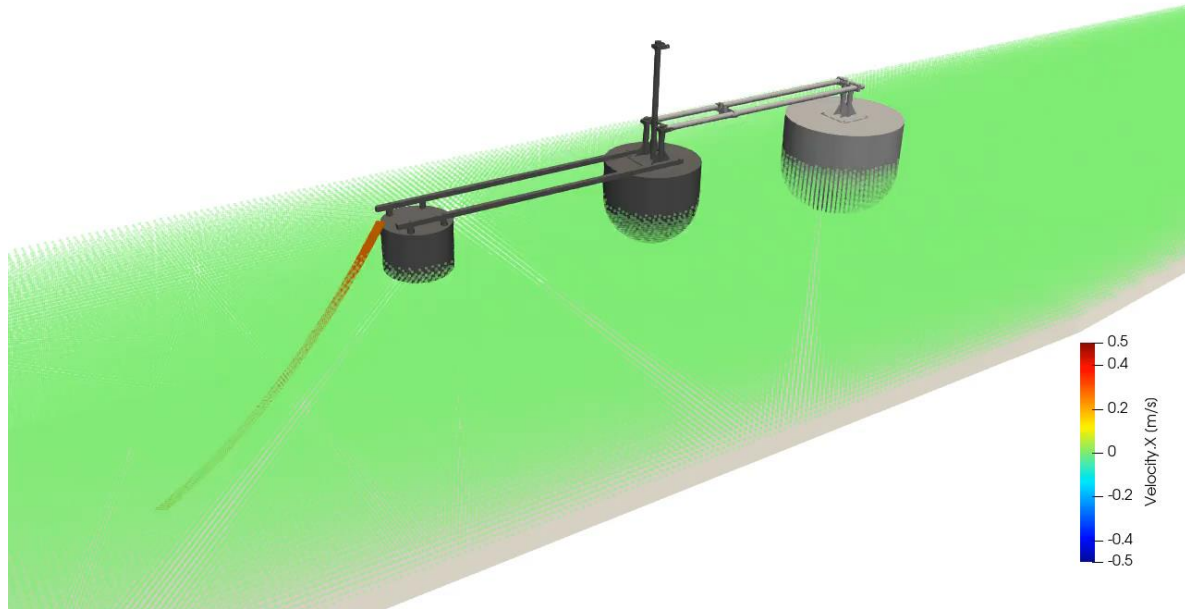
Source: *Santo et al., 2017*



## 2.4 Multi-float M4

### Validation using DualSPHysics v5.2

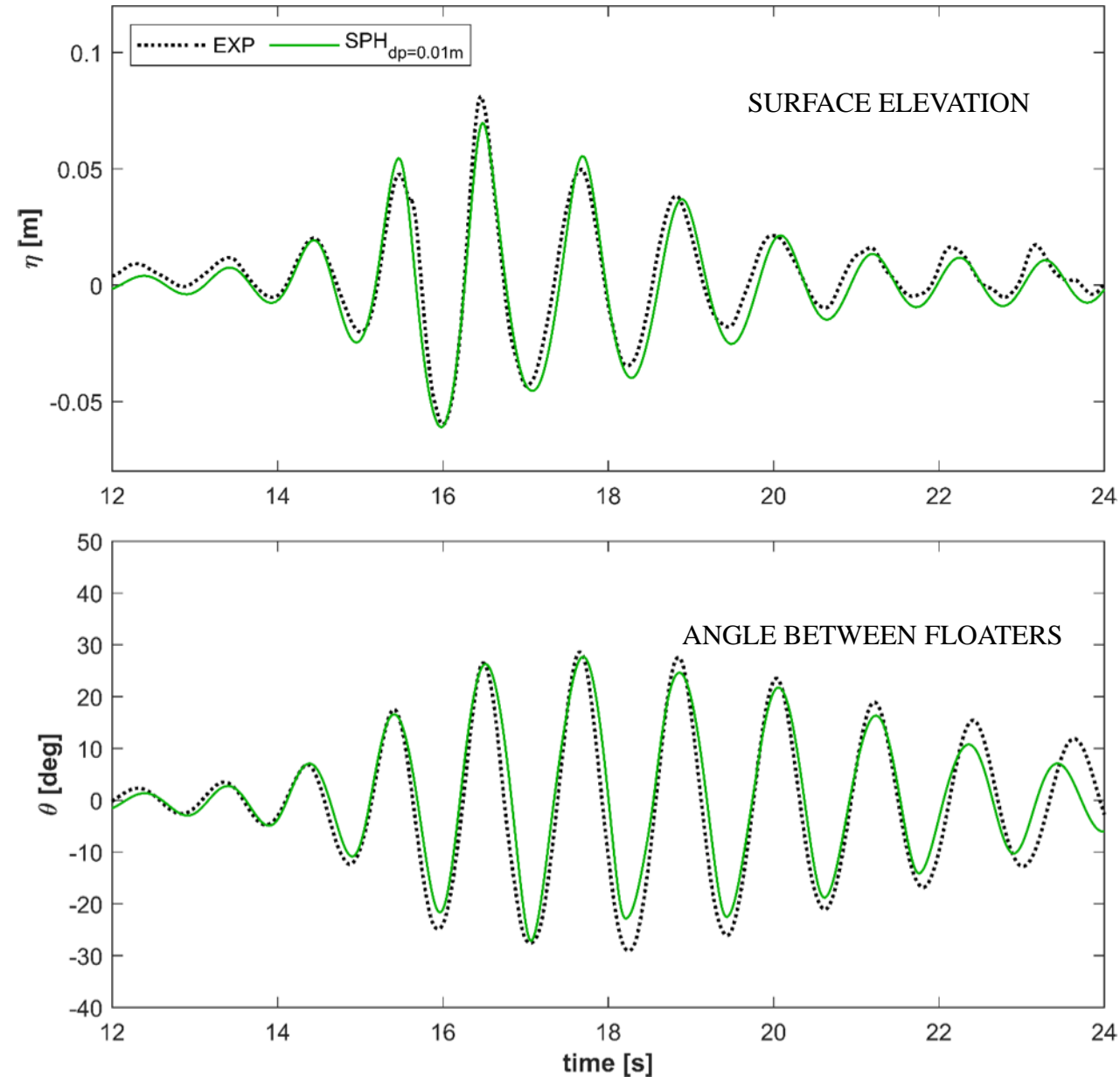
Time: 0.00 s



Focused wave ( $H_{focus}=0.16$  m,  $T_{focus}=1.1$  s, depth=0.6 m)



$dp$ [m]	0.03	0.02	0.01
$H/dp$	5.33	8.00	16.00
particles	$3.30 \cdot 10^5$	$1.20 \cdot 10^6$	$7.46 \cdot 10^6$
runtime	0.6 h	2.1 h	24.9 h
runtime/second	1.4 min	4.9 min	59.6 min



## Previous published work

### 2.1 Uppsala Point Absorber

Tagliaferro B, Martínez-Estévez I, Domínguez JM, Crespo AJC, Göteman M, Engström J, Gómez-Gesteira M. 2022. A numerical study of a taut-moored point-absorber wave energy converter with a linear power take-off system under extreme wave conditions. *Applied Energy*, 311, 118629.

### 2.2 Oscillating Wave Surge Converter

Brito M, Canelas RB, García-Feal O, Domínguez JM, Crespo AJC, Ferreira RML, Neves MG, Teixeira L. 2020. A numerical tool for modelling oscillating wave surge converter with nonlinear mechanical constraints. *Renewable Energy*, 146, 2024-2043.

### 2.3 Floating Oscillating Surge Wave Energy Converter


Tagliaferro B, Martínez-Estévez I, Crego-Loureiro C, Domínguez JM, Crespo AJC, Coe R, Bacelli G, Gómez Gesteira M, Viccione G. 2022. Numerical modeling of moored floating platforms for wave energy converters using DualSPHysics. In: *Proceedings of the 41st International Conference on Ocean, Offshore & Arctic Engineering, Hamburg, Germany. OMAE 2022*

### 2.4 Multi-float M4


Carpintero Moreno E, Fourtakas G, Crespo AJC, Stansby PK. 2020. Response of the multi-float WEC M4 in focussed waves using SPH. In: *4th International Conference on Renewable Energies Offshore, Lisbon, Portugal. RENEW 2020.*

Applied Energy 311 (2022) 118629

Contents lists available at ScienceDirect

 **Applied Energy**

journal homepage: [www.elsevier.com/locate/apenergy](http://www.elsevier.com/locate/apenergy)




A numerical study of a taut-moored point-absorber wave energy converter with a linear power take-off system under extreme wave conditions


Bonaventura Tagliaferro <sup>a</sup>, Iván Martínez-Estévez <sup>b</sup>, José M. Domínguez <sup>b</sup>, Alejandro J.C. Crespo <sup>b,\*</sup>, Malin Göteman <sup>c</sup>, Jens Engström <sup>c</sup>, Moncho Gómez-Gesteira <sup>b</sup>

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A numerical tool for modelling oscillating wave surge converter with nonlinear mechanical constraints

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# OUTLINE

## **1. Numerical modelling of WECs**

### **1.1 Meshless CFD and SPH**

### **1.2 DualSPHysics open-source code**

### **1.3 Coupling with other solvers**

## **2. Simulation of different WEC technologies**

### **2.1 Uppsala Point Absorber**

### **2.2 Oscillating Wave Surge Converter**

### **2.3 Floating Oscillating Surge Wave Energy Converter**

### **2.4 Multi-float M4**

## **3. Work undergoing**

### **3.1 More WEC technologies**

### **3.2 Active control systems**

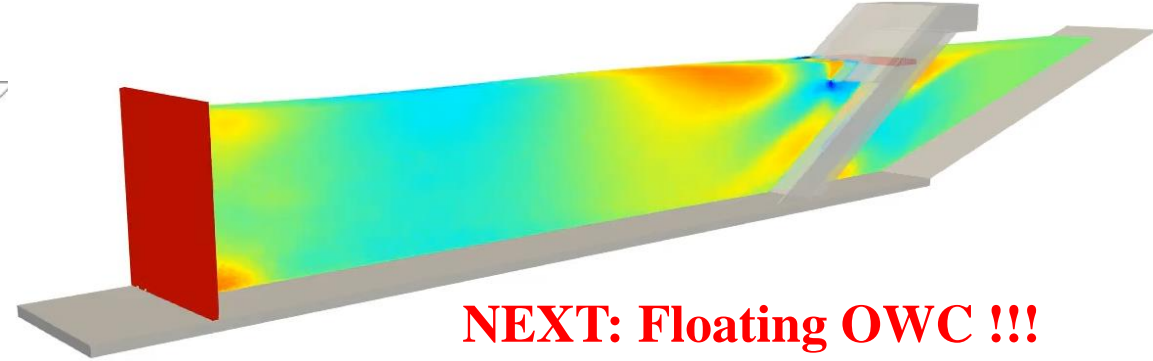
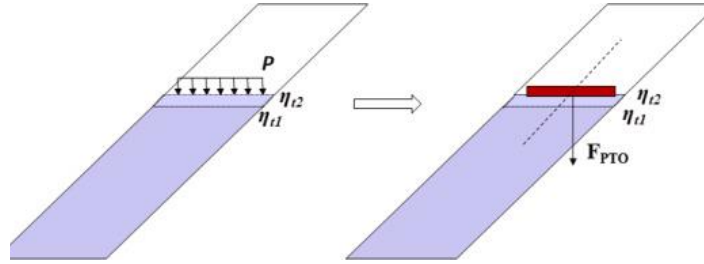
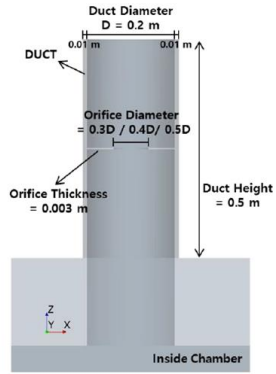
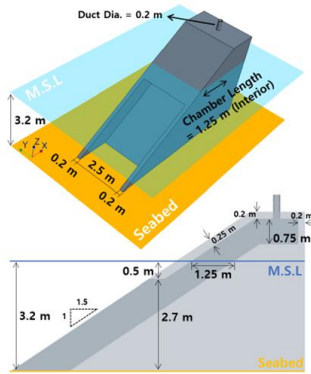
### **3.3 Flexible WECs**

## **4. Conclusions**

# 3.1 More WEC technologies

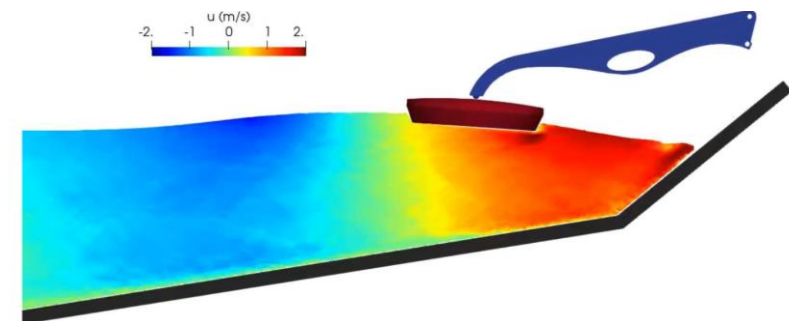
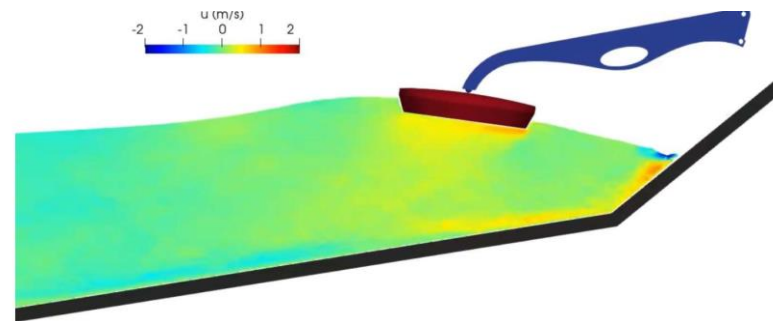
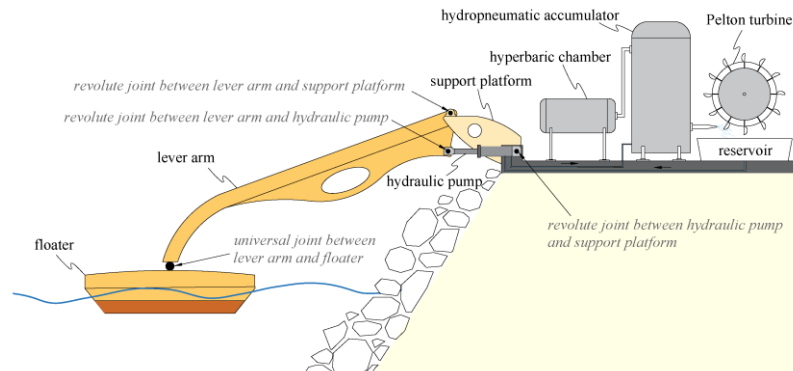
## OWC

*Quartier N, Crespo AJC, Domínguez JM, Stratigaki V, Troch P. 2021. Efficient response of an onshore Oscillating Water Column Wave Energy Converter using a one-phase SPH model coupled with a multiphysics library. Applied Ocean Research, 115, 102856.*



## WaveStar

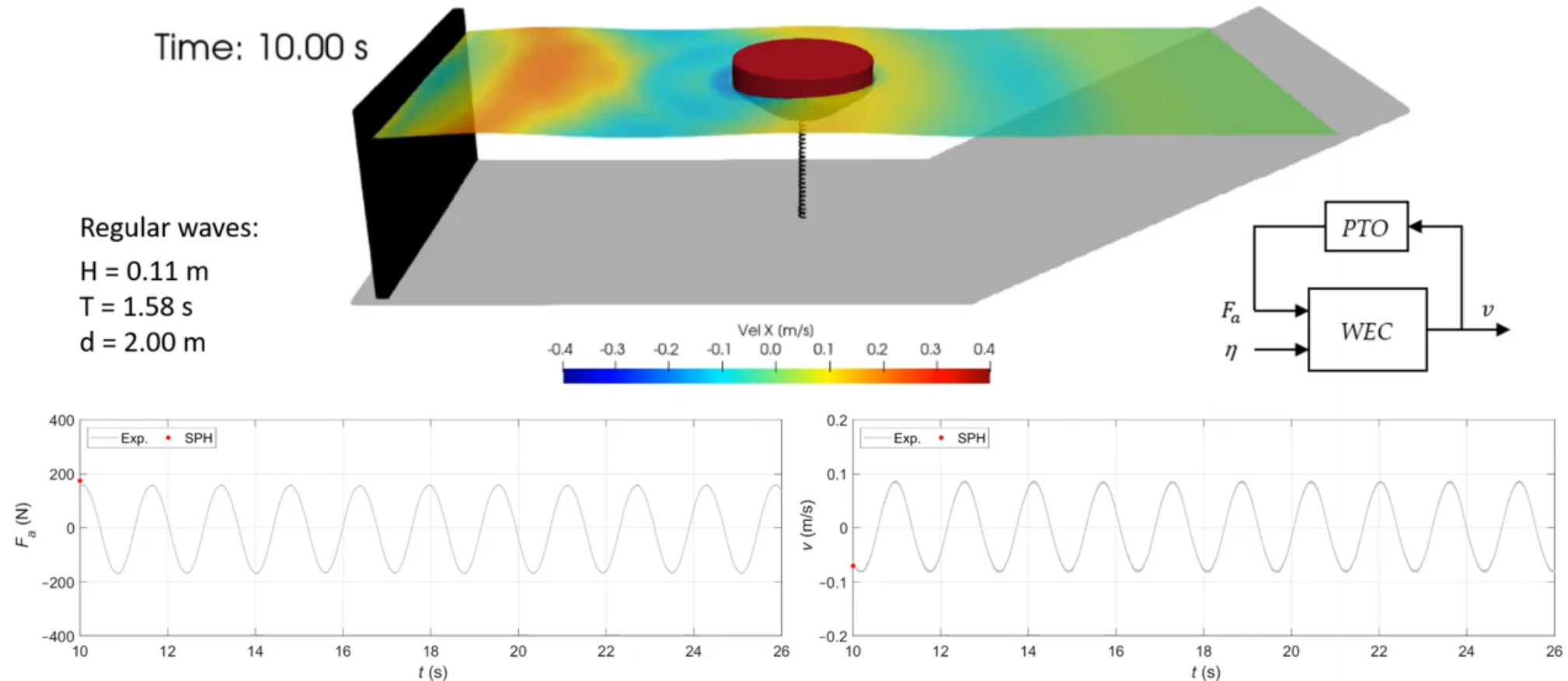
*Brito M, Bernardo F, Neves MG, Neves DRCB, Crespo AJC, Domínguez JM. 2022. Numerical Model of Constrained Wave Energy Hyperbaric Converter under Full-Scale Sea Wave Conditions. Journal of Marine Science and Engineering, 10(10), 1489.*



## 3.2 Active control systems

### CLOSED-LOOP SYSTEM CONTROLLER

Point absorber with a closed-loop system defining the **PTO** force as function of the **WEC's** position and velocity



Sandia National Laboratories is a multi-mission laboratory managed and operated by National Technology and Engineering Solutions of Sandia, LLC., a wholly owned subsidiary of Honeywell International, Inc., for the U.S. Department of Energy's National Nuclear Security Administration under contract DE-NA0003525.

*Ropero-Giralda P, Crespo AJC, Coe RG, Tagliaferro B, Domínguez JM, Bacelli G, Gómez-Gesteira M. 2021. Modelling a heaving point-absorber with a closed-loop control system using the DualSPHysics code. Energies 14(3), 760.*

## 3.3 Flexible WECs

### Numerical implementation of flexible-structure interaction (FSI)

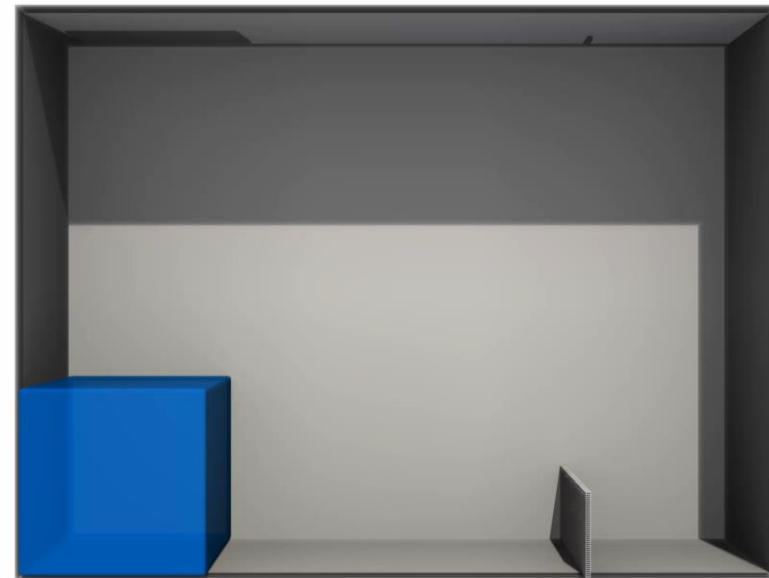
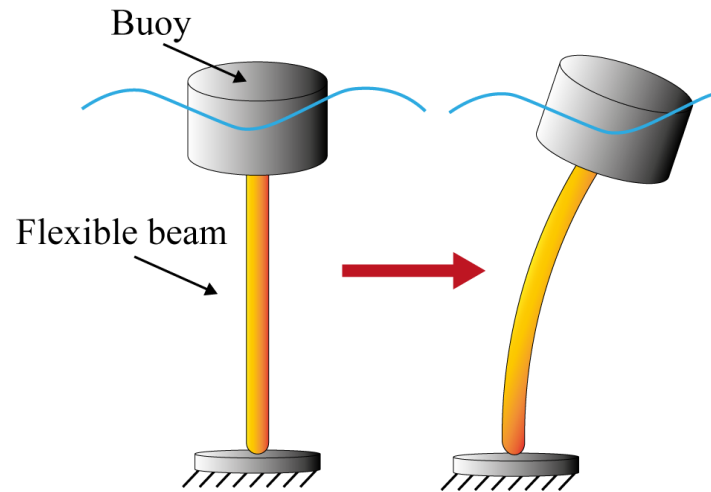
**OPTION 1:** Fully Lagrangian: SPH for fluid and total Lagrangian SPH for the solid solver

*O'Connor J, Rogers BD. 2021. A fluid-structure interaction model for free-surface flows and flexible structures using smoothed particle hydrodynamics on a GPU, [Journal of Fluids and Structures](#), 104, 103312.*

**OPTION 1** already in DualSPHysics v5.2

**OPTION 2:** Fully Lagrangian: SPH for fluid coupled with FEA module of Project Chrono

*Martínez-Estévez I, Tagliafierro B, El Rahi J, Domínguez JM, Crespo AJC, Troch P, Gómez-Gesteira M. 2023. Coupling an SPH-based solver with an FEA structural solver to simulate free surface flows interacting with flexible structures. [Computer Methods in Applied Mechanics and Engineering](#), 410, 115989.*



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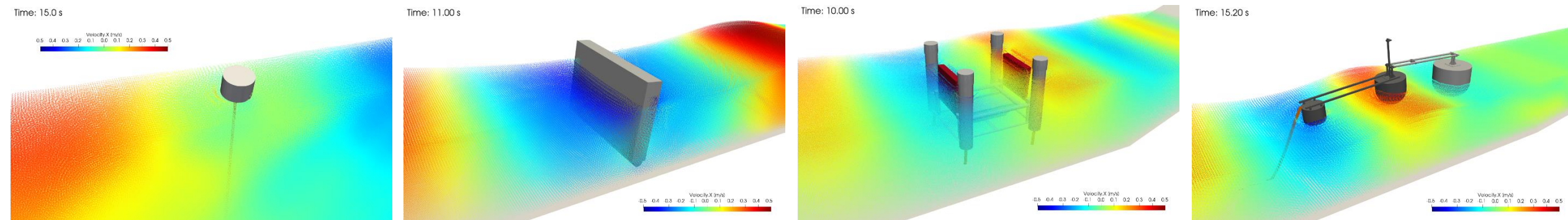
### OUR APPROACH

Meshless **SPH** method for **violent flows** with rapidly moving or **fluid-driven devices**

**DualSPHysics v5.2** is applied to **four well-established WEC concepts**

Study of not only the **efficiency** but **also the survivability** of WECs.

We provide a **free numerical tool** into simulating **other novel WEC devices**



### *Our message:*

- We have a mature technology to cope with any kind of device, no matter how complex it may be
- This numerical tool is capable of simulating devices under extreme waves including active control systems
- **We want you to collaborate with us! Please feel free to contact us!**



# WORK TEAM

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FIRENZE



UPPSALA  
UNIVERSITET

U. PORTO



Sandia  
National  
Laboratories

MANCHESTER  
1824

The University of Manchester

Simulating M4 WEC with DualSPHysics

Time: 9.94 s

Focused waves:  $T_p=1.0\text{s}$ ,  $A_c=0.08\text{m}$

**THANKS A LOT FOR  
YOUR ATTENTION**

**ESKERRIK ASKO** 

**MORE  
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